

## V.4. Pulse Shaping

### CR-RC shaper with unequal time constants

For simplicity, the preceding discussion assumed equal differentiator and integrator time constants.

Furthermore, the detector capacitance was the only capacitance present at the input. In reality this is never the case, but additional capacitance can easily be accounted for by replacing  $C_D$  by the total input capacitance  $C_i$ , i.e. the sum of all capacitances present at the input node.

#### 1. Noise voltage at shaper output

$$V_{no}^2 = \int_0^{\infty} \sum_k v_{ni,k}^2 \cdot G^2(\omega) d\omega$$

$$V_{no}^2 = \int_0^{\infty} (v_{nb}^2 + v_{np}^2 + v_{nr}^2 + v_{na}^2) \cdot G^2(\omega) d\omega$$

$$V_{no}^2 = \int_0^{\infty} \left( \frac{2q_e I_b}{(\omega C_i)^2} + \frac{4kTR_P}{1 + (\omega R_P C_i)^2} + 4kTR_S + v_{na}^2 \right) \cdot \left( \frac{\omega^2 \tau_d^2}{2\pi (1 + \omega^2 \tau_d^2)(1 + \omega^2 \tau_i^2)} \right) d\omega$$

$$V_{no}^2 = \frac{1}{4C_i^2} \left( \frac{4kT}{R_P} + 2q_e I_b \right) \frac{\tau_d^2}{\tau_d + \tau_i} + (4kTR_S + v_{na}^2) \frac{\tau_d}{\tau_i (\tau_d + \tau_i)} + A_f \frac{\tau_d^2}{\tau_d^2 + \tau_i^2} \ln \left( \frac{\tau_d}{\tau_i} \right)$$

## 2. Peak signal voltage at the shaper output

Assume the detector signal is a pulse of constant current with duration  $t_c$  (i.e. the signal charges ramps up linearly until  $t = t_c$ ).

At times  $t < t_c$

$$V_{so}(t) = V_o \left[ \frac{\tau_d}{t_c} (1 - e^{-t/\tau_i}) - \frac{\tau_d^2}{t_c(\tau_d - \tau_i)} (e^{-t/\tau_d} - e^{-t_c/\tau_i}) \right]$$

At times  $t > t_c$

$$V_{so}(t) = V_o \left[ \frac{\tau_d^2}{t_c(\tau_d - \tau_i)} (e^{t_c/\tau_i} - 1) e^{-t_c/\tau_d} - \frac{\tau_d \tau_i}{t_c(\tau_d - \tau_i)} (e^{t_c/\tau_i} - 1) e^{-t_c/\tau_i} \right]$$

The peak amplitude of the signal is

$$V_{so} = V_o \frac{\tau_d}{t_c} \frac{(e^{t_c/\tau_d} - 1)^{\tau_d/(\tau_d - \tau_i)}}{(e^{t_c/\tau_i} - 1)^{\tau_i/(\tau_d - \tau_i)}}$$

Assume that the shaper has no additional voltage gain. Then  $V_o$  is equal to the input signal voltage

$$V_o = V_i = \frac{Q_s}{C_i}$$

In the limit that the collection time is negligible,  $t_c \ll \tau_d, \tau_i$

$$V_{so} = \frac{Q_s}{C_i} f(\tau_d, \tau_i)$$

Furthermore, since the peak signal depends only on the ratios of time constants, i.e. it is independent of the absolute time scale

$$V_{so} = \frac{Q_s}{C_i} F_s(\tau_d / \tau_i)$$

The noise at the output, however, does depend on the time scale (as it determines the noise bandwidth).

$$V_{no}^2 = \frac{1}{4C_i^2} \left( \frac{4kT}{R_p} + 2q_e I_b \right) \frac{\tau_d^2}{\tau_d + \tau_i} + (4kTR_S + v_{na}^2) \frac{\tau_d}{\tau_i(\tau_d + \tau_i)} + A_f \frac{\tau_d^2}{\tau_d^2 + \tau_i^2} \ln \left( \frac{\tau_d}{\tau_i} \right)$$

First, to simplify the expression for the output noise, neglect the  $1/f$  term and combine the terms for

current noise

$$i_n^2 = 2q_e I_b + \frac{4kT}{R_p}$$

and voltage noise

$$v_n^2 = 4kTR_S + v_{na}^2$$

and introduce a characteristic time  $T$ , which initially will be set equal to the peaking time  $t_p$ . With these conventions

$$V_{no}^2 = \frac{1}{4C_i^2} i_n^2 T \frac{\tau_d}{t_p} \frac{\tau_d}{\tau_d + \tau_i} + v_n^2 \frac{1}{T} \frac{t_p}{\tau_i} \frac{\tau_d}{\tau_d + \tau_i}$$

Using the above results and reintroducing  $1/f$  noise,

$$V_{no}^2 = \frac{1}{4C_i^2} i_n^2 T \frac{\tau_d}{t_p} \frac{\tau_d}{\tau_d + \tau_i} + v_n^2 \frac{1}{T} \frac{t_p}{\tau_i} \frac{\tau_d}{\tau_d + \tau_i} + A_f \frac{\tau_d^2}{\tau_d^2 + \tau_i^2} \ln\left(\frac{\tau_d}{\tau_i}\right)$$

and

$$V_{so} = \frac{Q_s}{C_i} F_s(\tau_d / \tau_i)$$

the equivalent noise charge

$$Q_n = \frac{V_{no}}{V_{so}} Q_s$$

can be written as

$$Q_n^2 = i_n^2 T F_i + C_i^2 v_n^2 \frac{1}{T} F_v + C_i^2 A_f F_{vf}$$

where

$$F_i \equiv \frac{\tau_d}{4t_p} \frac{1}{1 + \tau_i / \tau_d} \frac{1}{F_s(\tau_d / \tau_i)}$$

$$F_v \equiv \frac{t_p}{\tau_i} \frac{1}{1 + \tau_i / \tau_d} \frac{1}{F_s(\tau_d / \tau_i)}$$

$$F_{vf} \equiv \frac{1}{1 + (\tau_i / \tau_d)^2} \ln\left(\frac{\tau_d}{\tau_i}\right) \frac{1}{F_s(\tau_d / \tau_i)}$$

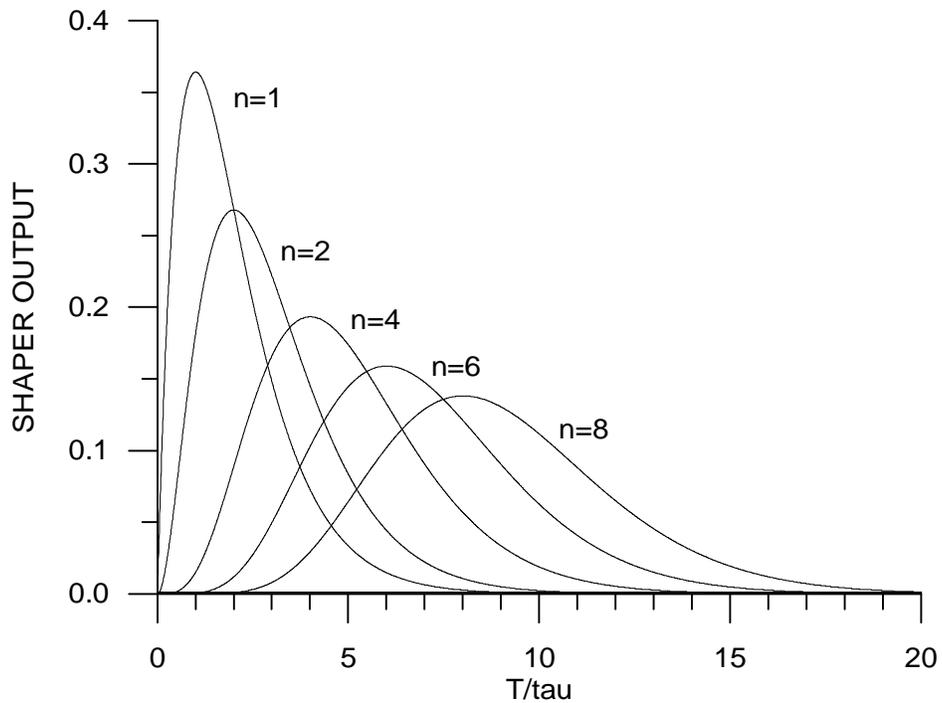
The noise indices or “form factors”  $F_i$ ,  $F_v$  and  $F_{vf}$  characterize a type of shaper, for example  $CR-RC$  or  $CR-(RC)^4$ .

They depend only on the ratio of time constants  $\tau_d/\tau_i$ , rather than their absolute magnitude.

The noise contribution then scales with the characteristic time  $T$ . The choice of characteristic time is somewhat arbitrary. so any convenient measure for a given shaper can be adopted in deriving the noise coefficients  $F$ .

## CR-RC Shapers with Multiple Integrators

- a. Start with simple *CR-RC* shaper and add additional integrators ( $n= 1$  to  $n= 2, \dots n= 8$ ) with the same time constant  $\tau$  .

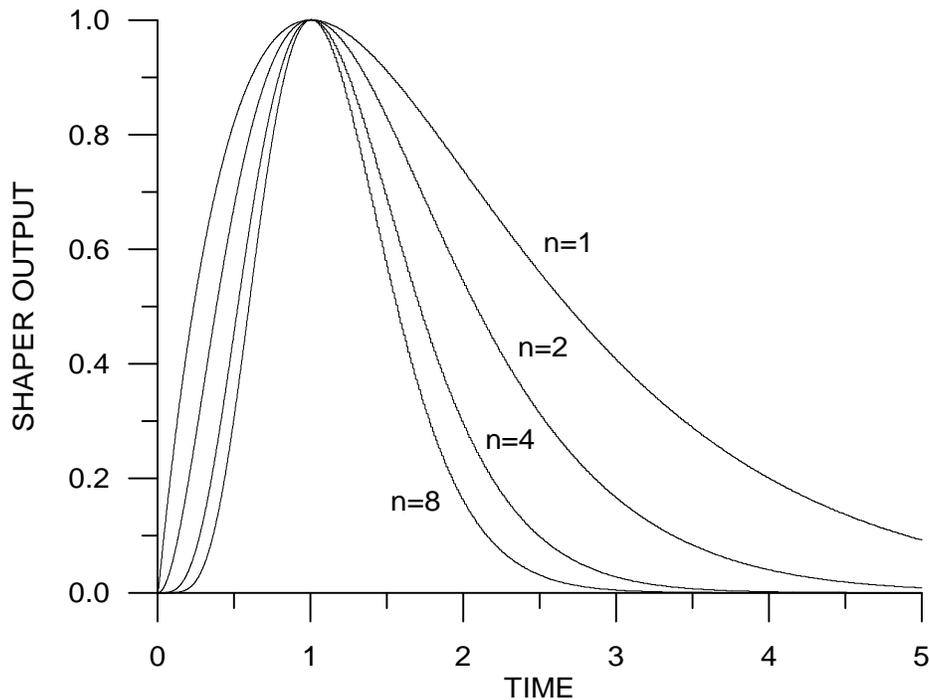


With additional integrators the peaking time  $T_p$  increases

$$T_p = n\tau$$

b) Time constants changed to preserve the peaking time

$$(\tau_n = \tau_{n=1}/n)$$



Increasing the number of integrators makes the output pulse more symmetrical with a faster return to baseline.

⇒ improved rate capability at the same peaking time

Shapers with the equivalent of 8  $RC$  integrators are common. Usually, this is achieved with active filters (i.e. circuitry that synthesizes the bandpass with amplifiers and feedback networks).



The noise analysis of shapers is rather straightforward if the frequency response is known.

On the other hand, since we are primarily interested in the pulse response, shapers are often designed directly in the time domain, so it seems more appropriate to analyze the noise performance in the time domain also.

Clearly, one can take the time response and Fourier transform it to the frequency domain, but this approach becomes problematic for time-variant shapers.

The CR-RC shapers discussed up to now utilize filters whose time constants remain constant during the duration of the pulse, i.e. they are time-invariant.

Many popular types of shapers utilize signal sampling or change the filter constants during the pulse to improve pulse characteristics, i.e. faster return to baseline or greater insensitivity to variations in detector pulse shape.

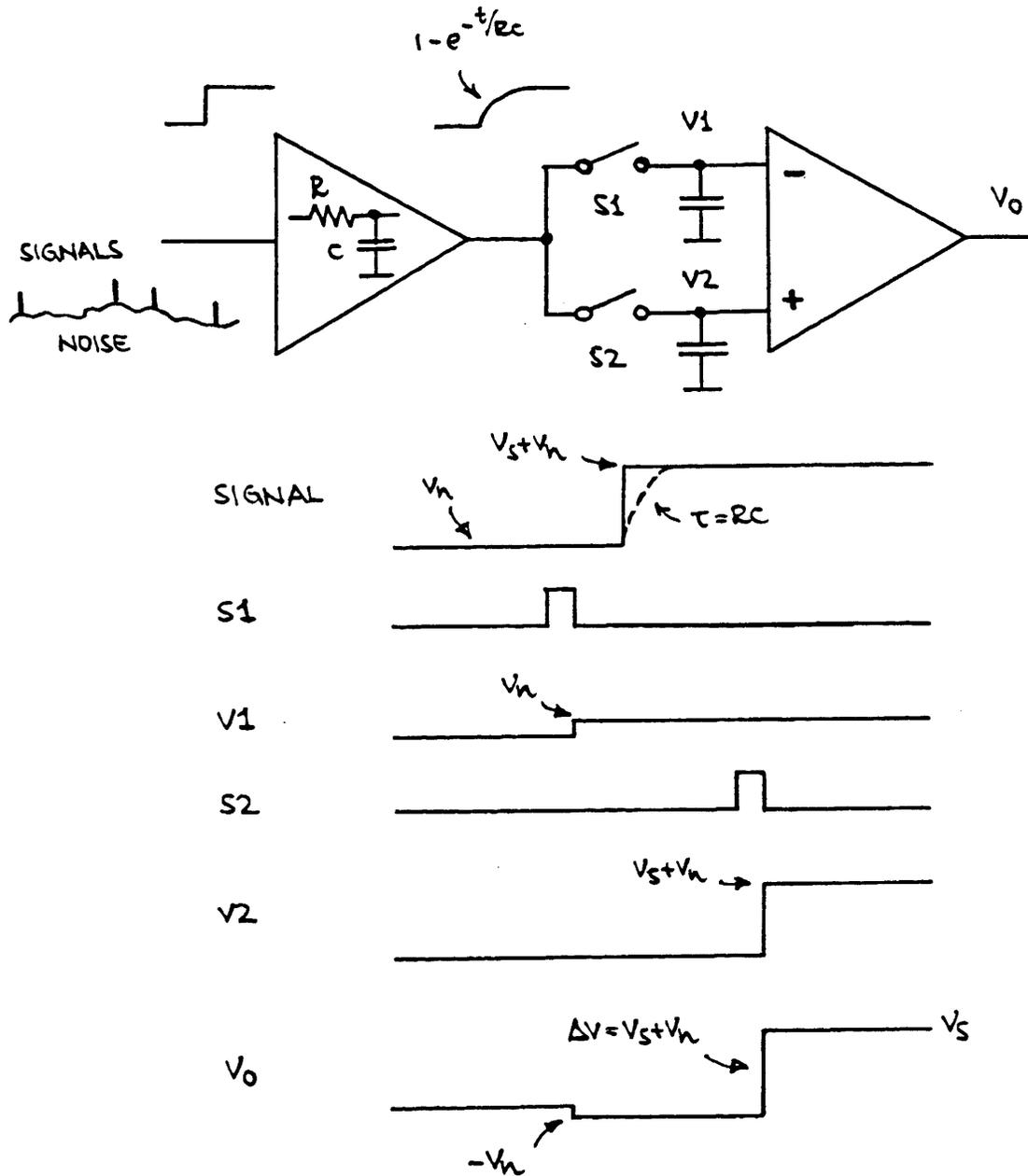
These time-variant shapers cannot be analyzed in the manner described above. Various techniques are available, but some shapers can be analyzed only in the time domain.

Example:

A commonly used time-variant filter is the correlated double-sampler.

This shaper can be analyzed exactly only in the time domain.

## Correlated Double Sampling



1. Signals are superimposed on a (slowly) fluctuating baseline
2. To remove baseline fluctuations the baseline is sampled prior to the arrival of a signal.
3. Next, the signal + baseline is sampled and the previous baseline sample subtracted to obtain the signal

## Noise Analysis in the Time Domain

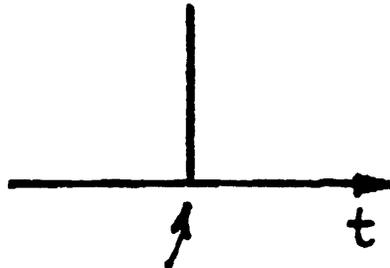
What pulse shapes have a frequency spectrum corresponding to typical noise sources?

### 1. voltage noise

The frequency spectrum at the input of the detector system is “white”, i.e.

$$\frac{dA}{df} = \text{const.}$$

This is the spectrum of a  $\delta$  impulse:



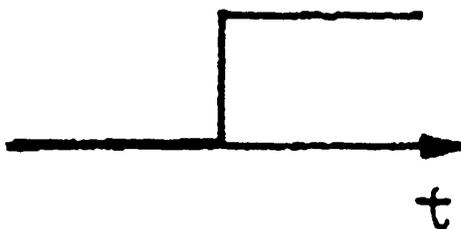
infinitesimally narrow,  
but area= 1.

### 2. current noise

The spectral density is inversely proportional to frequency, i.e.

$$\frac{dA}{df} \propto \frac{1}{f}$$

This is the spectrum of a step impulse:



- Input noise can be considered as a sequence of  $\delta$  and step pulses whose rate determines the noise level.
- The shape of the primary noise pulses is modified by the pulse shaper:

$\delta$  pulses become longer,

step pulses are shortened.

- The noise level at a given measurement time  $T_m$  is determined by the cumulative effect (superposition) of all noise pulses occurring prior to  $T_m$ .
- Their individual contributions at  $t = T_m$  are described by the shaper's "weighting function"  $W(t)$ .

#### References:

- V. Radeka, Nucl. Instr. and Meth. **99** (1972) 525  
V. Radeka, IEEE Trans. Nucl. Sci. **NS-21** (1974) 51  
F.S. Goulding, Nucl. Instr. and Meth. **100** (1972) 493  
F.S. Goulding, IEEE Trans. Nucl. Sci. **NS-29** (1982) 1125

Consider a single noise pulse occurring in a short time interval  $dt$  at a time  $T$  prior to the measurement. The amplitude at  $t = T$  is

$$a_n = W(T)$$



If, on the average,  $n_n dt$  noise pulses occur within  $dt$ , the fluctuation of their cumulative signal level at  $t = T$  is proportional to

$$\sqrt{n_n dt}$$

The magnitude of the baseline fluctuation is

$$\sigma_n^2(T) \propto n_n [W(t)]^2 dt$$

For all noise pulses occurring prior to the measurement

$$\sigma_n^2 \propto n_n \int_0^{\infty} [W(t)]^2 dt$$

where

$n_n$  determines the magnitude of the noise

and

$\int_0^{\infty} [W(t)]^2 dt$  describes the noise characteristics of the shaper – the “noise index”

# The Weighting Function

a) current noise

$W_i(t)$  is the shaper response to a step pulse, i.e. the “normal” output waveform.

b) voltage noise

$$W_v(t) = \frac{d}{dt} W_i(t) \equiv W'(t)$$

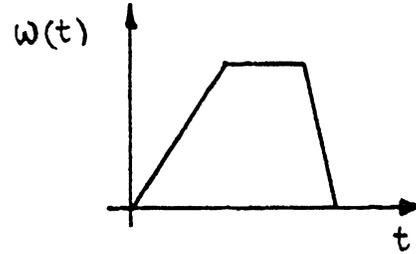
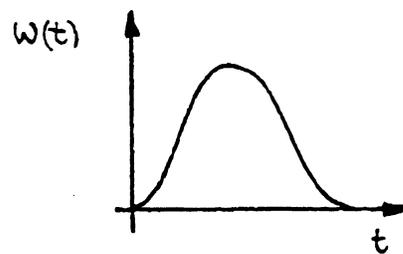
(Consider a  $\delta$  pulse as the superposition of two step pulses of opposite polarity and spaced infinitesimally in time)

Examples:

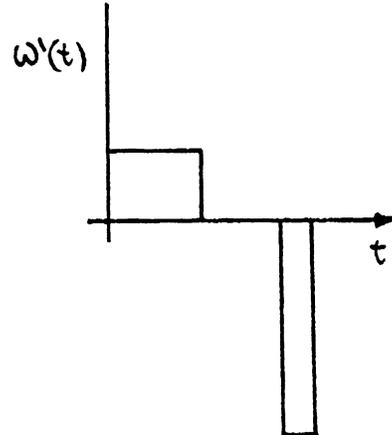
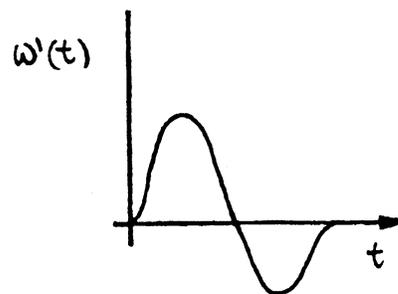
1. Gaussian

2. Trapezoid

current  
 (“step”)  
 noise



voltage  
 (“delta”)  
 noise



Goal: Minimize overall area

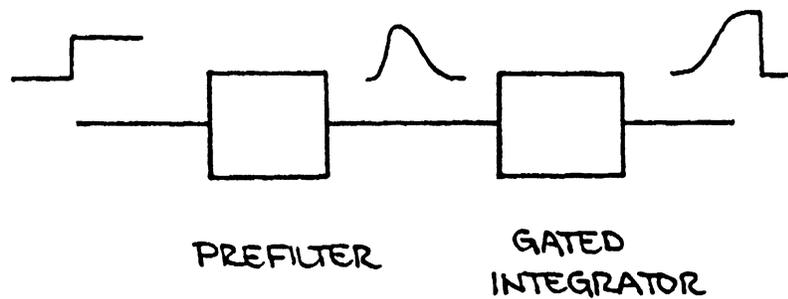
⇒ For a given pulse duration a symmetrical pulse provides the best noise performance.

## Time-Variant Shapers

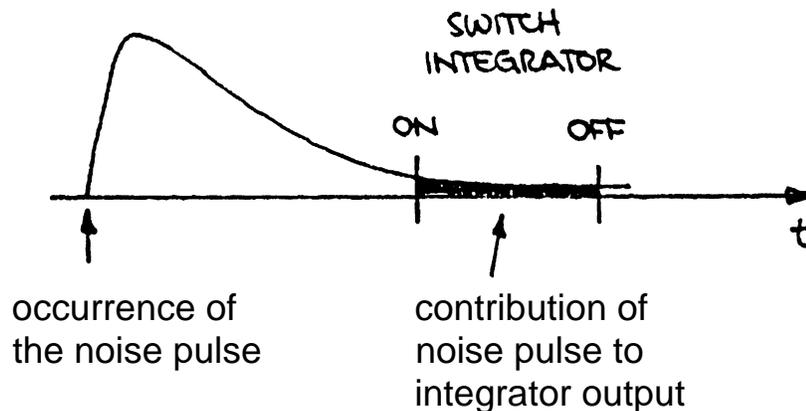
Example: gated integrator with prefilter

The gated integrator integrates the input signal during a selectable time interval (the “gate”).

In this example, the integrator is switched on prior to the signal pulse and switched off after a fixed time interval, selected to allow the output signal to reach its maximum.



Consider a noise pulse occurring prior to the “on time” of the integrator.



For  $W_1 =$  weighting function of the time-invariant prefilter

$W_2 =$  weighting function of the time-variant stage

the overall weighting function is obtained by convolution

$$W(t) = \int_{-\infty}^{\infty} W_2(t') \cdot W_1(t - t') dt'$$

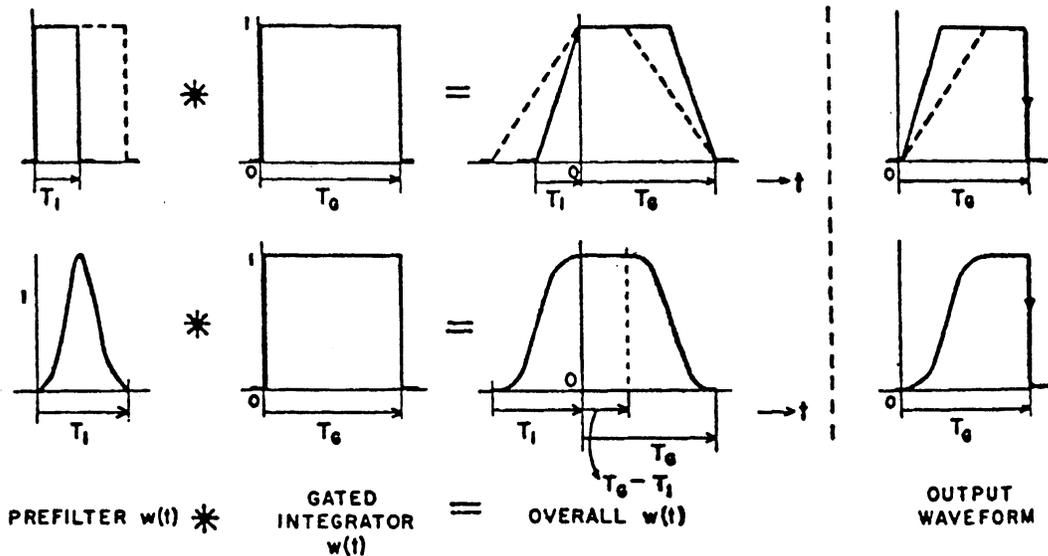
Weighting function for current ("step") noise:  $W(t)$

Weighting function for voltage ("delta") noise:  $W'(t)$

Example

Time-invariant prefilter feeding a gated integrator

(from Radeka, IEEE Trans. Nucl. Sci. **NS-19** (1972) 412)



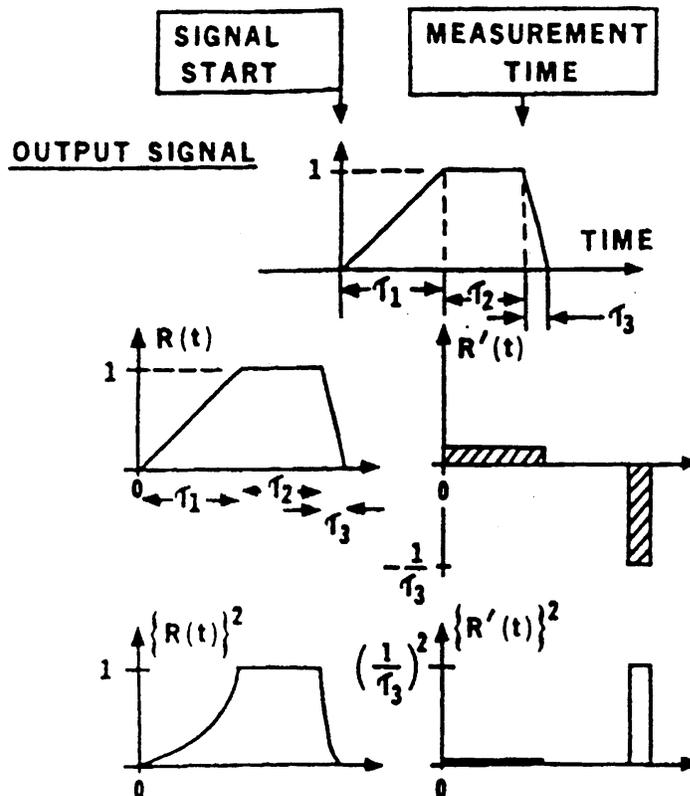
Comparison between a time-invariant and time-variant shaper  
 (from Goulding, NIM **100** (1972) 397)

Example: trapezoidal shaper

Duration= 2  $\mu$ s

Flat top= 0.2  $\mu$ s

1. Time-Invariant Trapezoid



Current noise

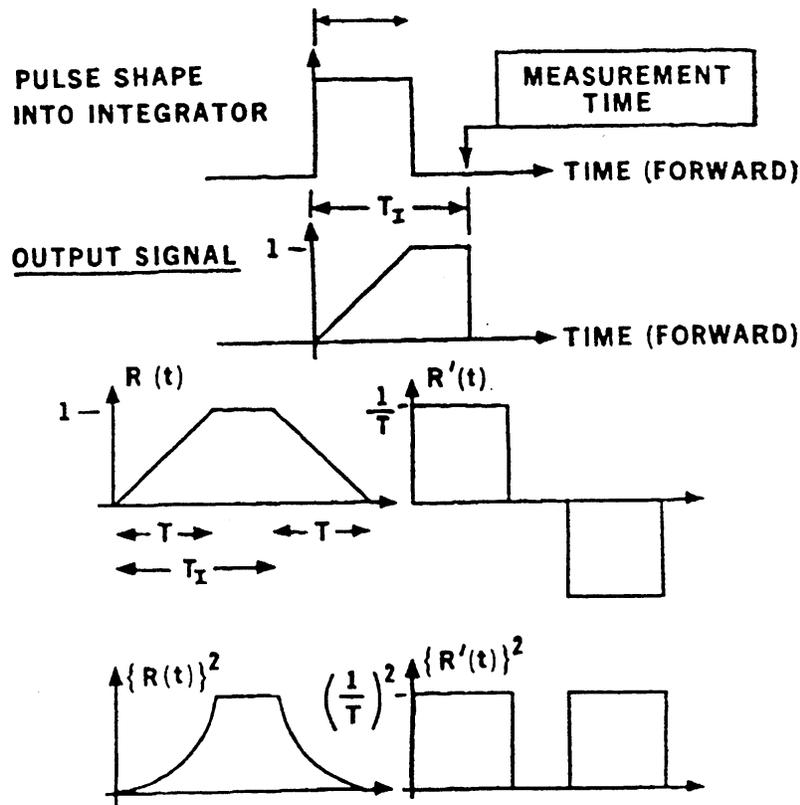
$$N_i^2 = \int_0^{\infty} [W(t)]^2 dt = \int_0^{\tau_1} \left(\frac{t}{\tau_1}\right)^2 dt + \int_{\tau_1}^{\tau_2} (1)^2 dt + \int_{\tau_2}^{\tau_3} \left(\frac{t}{\tau_3}\right)^2 dt = \tau_2 + \frac{\tau_1 + \tau_3}{3}$$

Voltage noise

$$N_v^2 = \int_0^{\infty} [W'(t)]^2 dt = \int_0^{\tau_1} \left(\frac{1}{\tau_1}\right)^2 dt + \int_{\tau_2}^{\tau_3} \left(\frac{1}{\tau_3}\right)^2 dt = \frac{1}{\tau_1} + \frac{1}{\tau_3}$$

Minimum for  $\tau_1 = \tau_3$  (symmetry!)  $\Rightarrow N_i^2 = 0.8, N_v^2 = 2.2$

## Gated Integrator Trapezoidal Shaper



## Current Noise

$$N_i^2 = 2 \int_0^T \left( \frac{t}{T} \right)^2 dt + \int_T^{T_I-T} (1)^2 dt = T_I - \frac{T}{3}$$

## Voltage Noise

$$N_v^2 = 2 \int_0^T \left( \frac{1}{T} \right)^2 dt = \frac{2}{T}$$

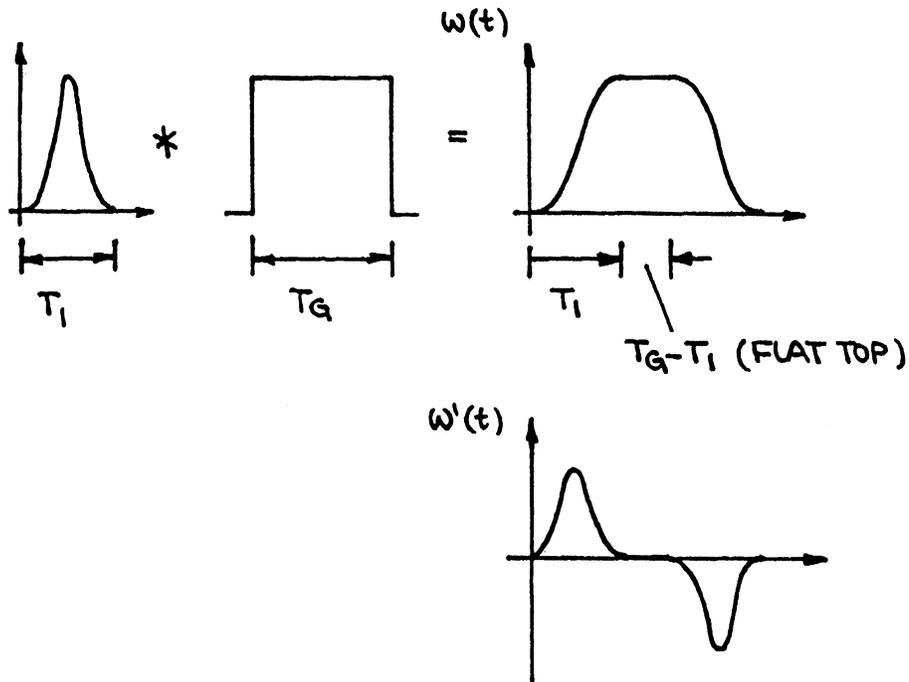
⇒ time-variant shaper  $N_i^2 = 1.4$ ,  $N_v^2 = 1.1$

time-invariant shaper  $N_i^2 = 0.8$ ,  $N_v^2 = 2.2$

time-variant trapezoid has more current noise, less voltage noise

## Interpretation of Results

Example: gated integrator



Current Noise

$$Q_{ni}^2 \propto \int [W(t)]^2 dt$$

Increases with  $T_I$  and  $T_G$  ( i.e. width of  $W(t)$  )

( more noise pulses accumulate within width of  $W(t)$  )

Voltage Noise

$$Q_{nv}^2 \propto \int [W'(t)]^2 dt$$

Increases with the magnitude of the derivative of  $W(t)$

( steep slopes  $\rightarrow$  large bandwidth — *determined by prefilter* )

Width of flat top irrelevant

(  $\delta$  response of prefilter is bipolar: net= 0 )

# Quantitative Assessment of Noise in the Time Domain

(see Radeka, IEEE Trans. Nucl. Sci. **NS-21** (1974) 51 )

$$Q_n^2 = \frac{1}{2} i_n^2 \int_{-\infty}^{\infty} [W(t)]^2 dt + \frac{1}{2} C_i^2 v_n^2 \int_{-\infty}^{\infty} [W'(t)]^2 dt$$

↑  
current noise

↑  
voltage noise

$Q_n$  = equivalent noise charge [C]

$i_n$  = input current noise spectral density [A/ $\sqrt{\text{Hz}}$ ]

$v_n$  = input voltage noise spectral density [V/ $\sqrt{\text{Hz}}$ ]

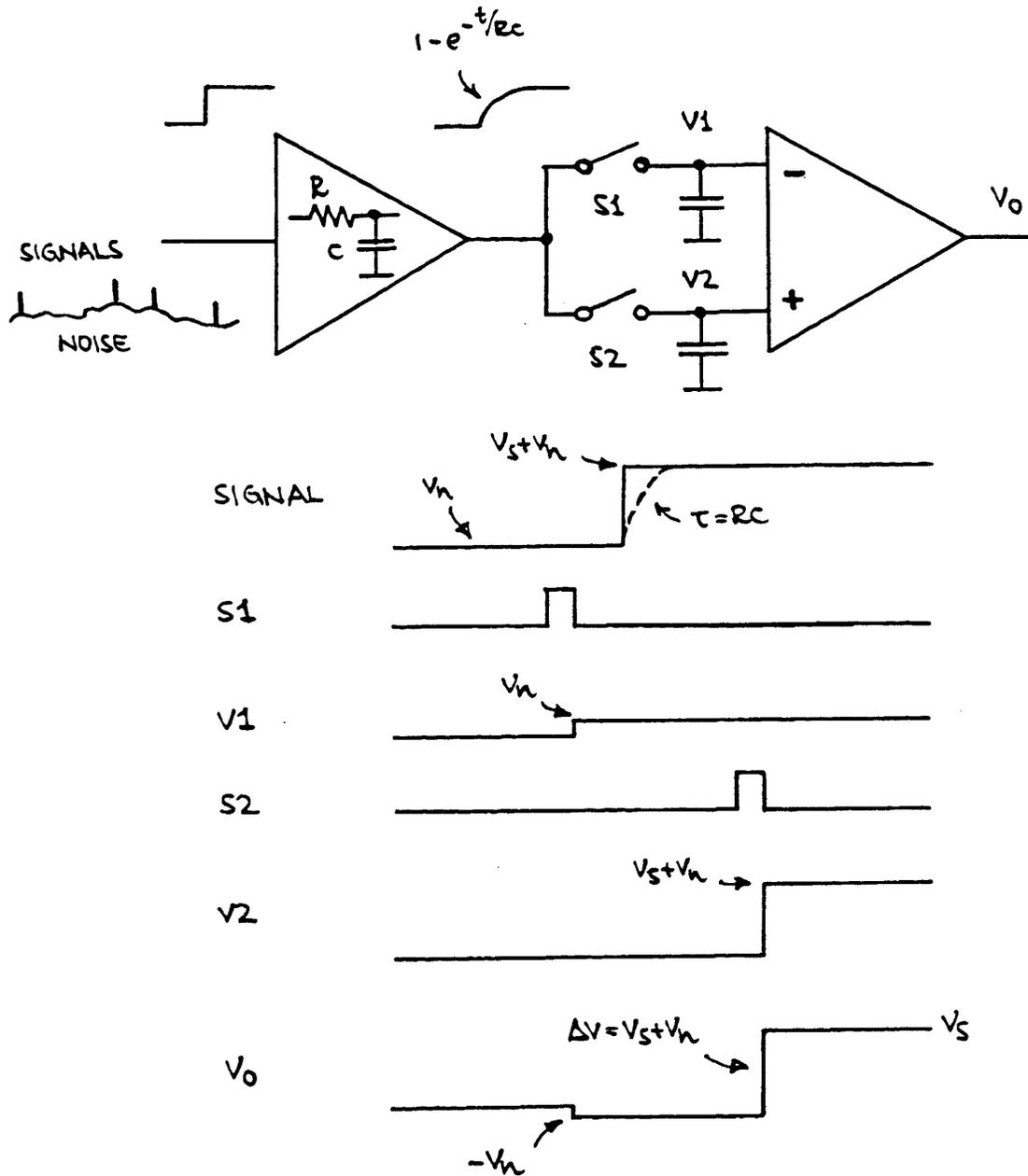
$C_i$  = total capacitance at input

$W(t)$  normalized to unit input step response

or rewritten in terms of a characteristic time  $t \rightarrow T/t$

$$Q_n^2 = \frac{1}{2} i_n^2 T \int_{-\infty}^{\infty} [W(t)]^2 dt + \frac{1}{2} C_i^2 v_n^2 \frac{1}{T} \int_{-\infty}^{\infty} [W'(t)]^2 dt$$

## Correlated Double Sampling



1. Signals are superimposed on a (slowly) fluctuating baseline
2. To remove baseline fluctuations the baseline is sampled prior to the arrival of a signal.
3. Next, the signal + baseline is sampled and the previous baseline sample subtracted to obtain the signal

## 1. Current Noise

Current (shot) noise contribution:

$$Q_{ni}^2 = \frac{1}{2} i_n^2 \int_{-\infty}^{\infty} [W(t)]^2 dt$$

Weighting function ( $T$  = time between samples):

$$t < 0: \quad W(t) = 0$$

$$0 \leq t \leq T: \quad W(t) = 1 - e^{-t/\tau}$$

$$t > T: \quad W(t) = e^{-(t-T)/\tau}$$

Current noise coefficient

$$F_i = \int_{-\infty}^{\infty} [W(t)]^2 dt$$

$$F_i = \int_0^T (1 - e^{-t/\tau})^2 dt + \int_T^{\infty} e^{-2(t-T)/\tau} dt$$

$$F_i = \left( T + \frac{\tau}{2} e^{-T/\tau} - \frac{\tau}{2} e^{-2T/\tau} \right) + \frac{\tau}{2}$$

so that the equivalent noise charge

$$Q_{ni}^2 = \frac{1}{2} i_n^2 \left[ T + \frac{\tau}{2} (e^{-T/\tau} - e^{-2T/\tau} + 1) \right]$$

$$Q_{ni}^2 = i_n^2 \tau \frac{1}{4} \left( \frac{2T}{\tau} + e^{-T/\tau} - e^{-2T/\tau} + 1 \right)$$

## Reality Check 1:

Assume that the current noise is pure shot noise

$$i_n^2 = 2q_e I$$

so that

$$Q_{ni}^2 = q_e I \tau \frac{1}{2} \left( \frac{2T}{\tau} + e^{-T/\tau} - e^{-2T/\tau} + 1 \right)$$

Consider the limit      Sampling Interval  $\gg$  Rise Time,  $T \gg \tau$  :

$$Q_{ni}^2 \approx q_e I \cdot T$$

or expressed in electrons

$$Q_{ni}^2 \approx \frac{q_e I \cdot T}{q_e^2} = \frac{I \cdot T}{q_e}$$

$$Q_{ni} \approx \sqrt{N_i}$$

where  $N_i$  is the number of electrons “counted” during the sampling interval  $T$ .

## 2. Voltage Noise

Voltage Noise Contribution

$$Q_{nv}^2 = \frac{1}{2} C_i^2 v_n^2 \int_{-\infty}^{\infty} [W'(t)]^2 dt$$

Voltage Noise Coefficient

$$F_v = \int_{-\infty}^{\infty} [W'(t)]^2 dt$$
$$F_v = \int_0^T \left( \frac{1}{\tau} e^{-t/\tau} \right)^2 dt + \int_T^{\infty} \left( \frac{1}{\tau} e^{-2(t-T)/\tau} \right)^2 dt$$
$$F_v = \frac{1}{2\tau} (1 - e^{-2T/\tau}) + \frac{1}{2\tau}$$
$$F_v = \frac{1}{2\tau} (2 - e^{-2T/\tau})$$

so that the equivalent noise charge

$$Q_{nv}^2 = C_i^2 v_n^2 \frac{1}{\tau} \frac{1}{4} (2 - e^{-2T/\tau})$$

## Reality Check 2:

In the limit  $T \gg \tau$  :

$$Q_{nv}^2 = C_i^2 \cdot v_n^2 \cdot \frac{1}{2\tau}$$

Compare this with the noise on an RC low-pass filter alone (i.e. the voltage noise at the output of the pre-filter):

$$Q_n^2(RC) = C_i^2 \cdot v_n^2 \cdot \frac{1}{4\tau}$$

(see the discussion on noise bandwidth)

so that

$$\frac{Q_n(\text{double sample})}{Q_n(RC)} = \sqrt{2}$$

If the sample time is sufficiently large, the noise samples taken at the two sample times are uncorrelated, so the two samples simply add in quadrature.

### 3. Signal Response

The preceding calculations are only valid for a signal response of unity, which is valid at  $T \gg \tau$ .

For sampling times  $T$  of order  $\tau$  or smaller one must correct for the reduction in signal amplitude at the output of the prefilter

$$V_s / V_i = 1 - e^{-T/\tau}$$

so that the equivalent noise charge due to the current noise becomes

$$Q_{ni}^2 = i_n^2 \tau \frac{\frac{2T}{\tau} + e^{-T/\tau} - e^{-2T/\tau} + 1}{4(1 - e^{-T/\tau})^2}$$

The voltage noise contribution is

$$Q_{nv}^2 = C_i^2 v_n^2 \frac{1}{\tau} \frac{2 - e^{-2T/\tau}}{4(1 - e^{-T/\tau})^2}$$

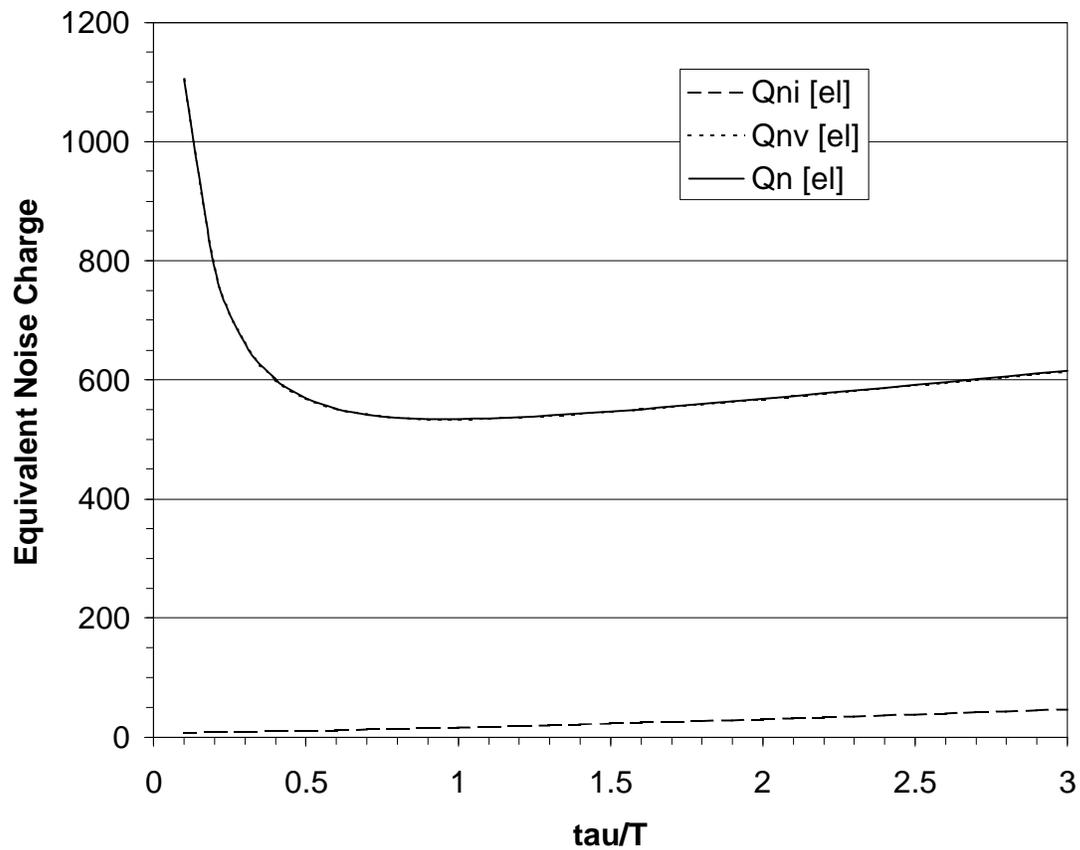
and the total equivalent noise charge

$$Q_n = \sqrt{Q_{ni}^2 + Q_{nv}^2}$$

# Optimization

## 1. Noise current negligible

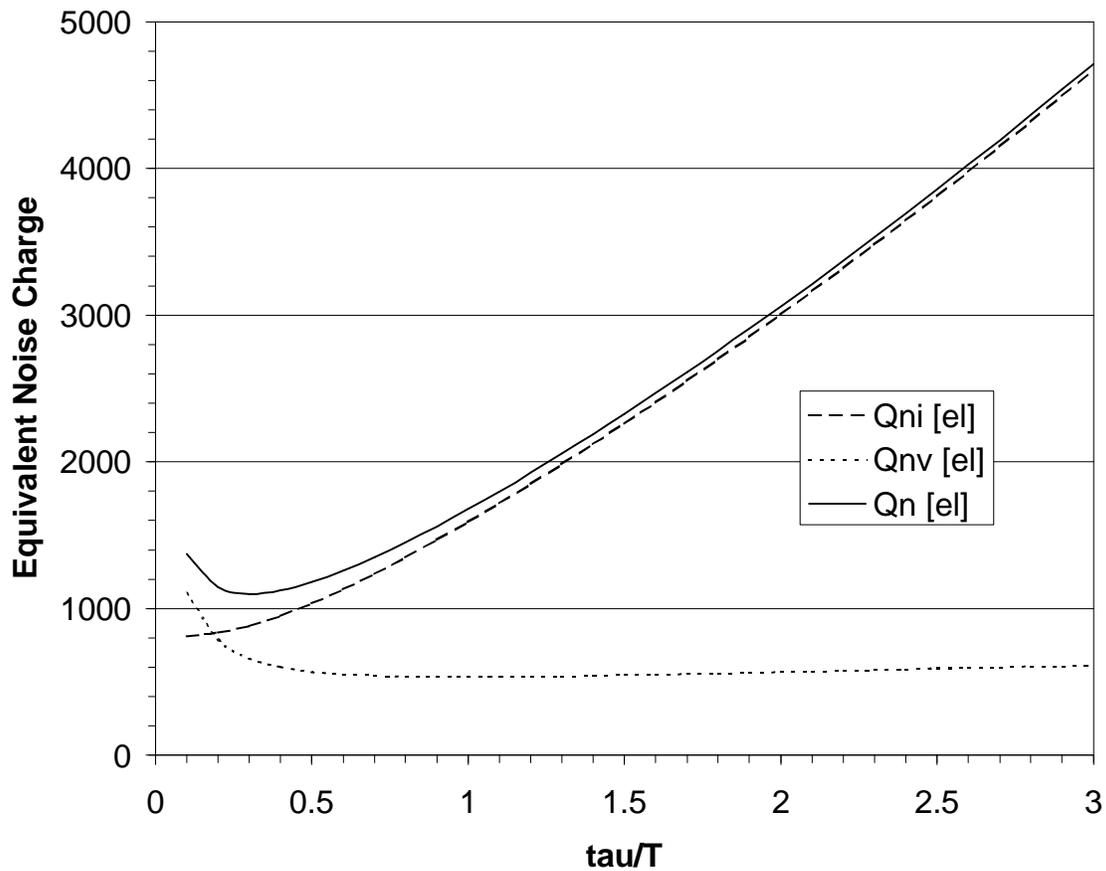
Parameters:  $T = 100$  ns  
 $C_d = 10$  pF  
 $v_n = 2.5$  nV/ $\sqrt{\text{Hz}}$   
 $\rightarrow i_n = 6$  fA/ $\sqrt{\text{Hz}}$  ( $I_b = 0.1$  nA)



Noise attains shallow minimum for  $\tau = T$ .

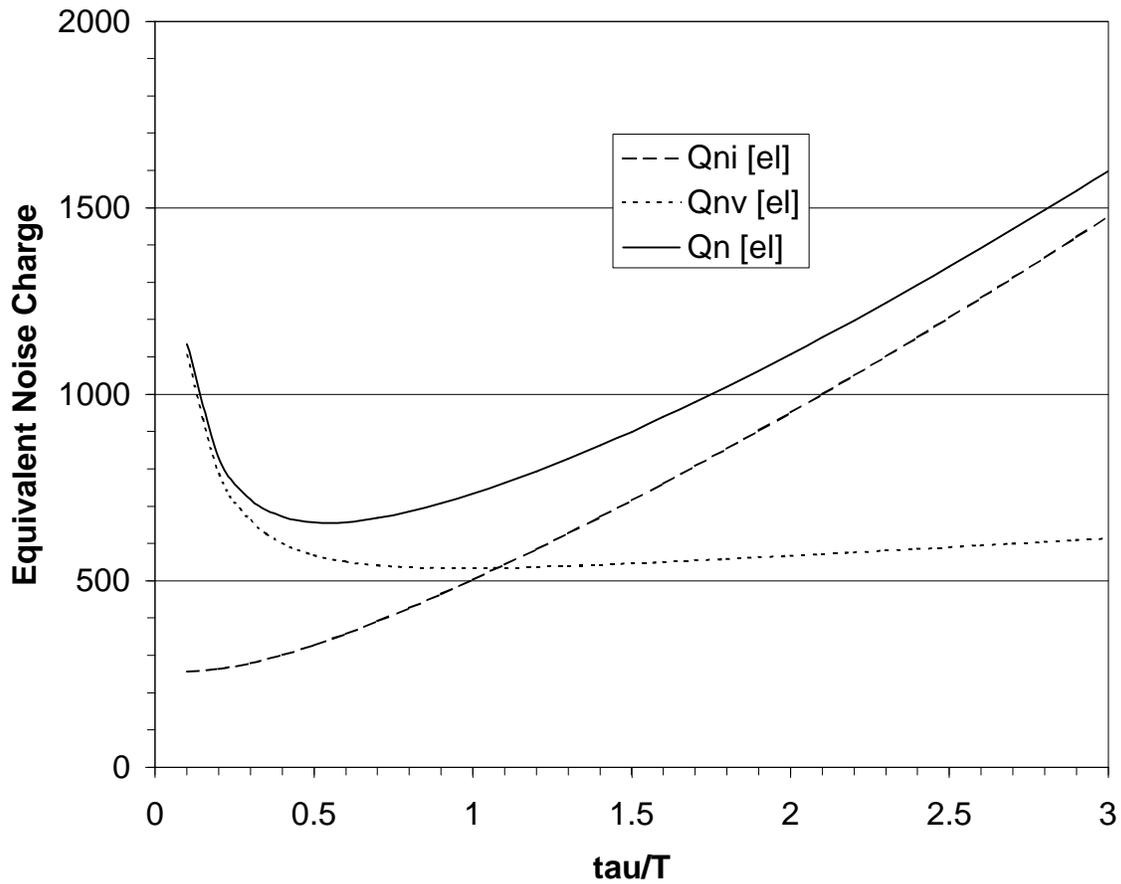
## 2. Significant current noise contribution

Parameters:  $T = 100 \text{ ns}$   
 $C_d = 10 \text{ pF}$   
 $v_n = 2.5 \text{ nV}/\sqrt{\text{Hz}}$   
 $\rightarrow i_n = 0.6 \text{ pA}/\sqrt{\text{Hz}} \quad (I_b = 1 \text{ }\mu\text{A})$



Noise attains minimum for  $\tau = 0.3 T$ .

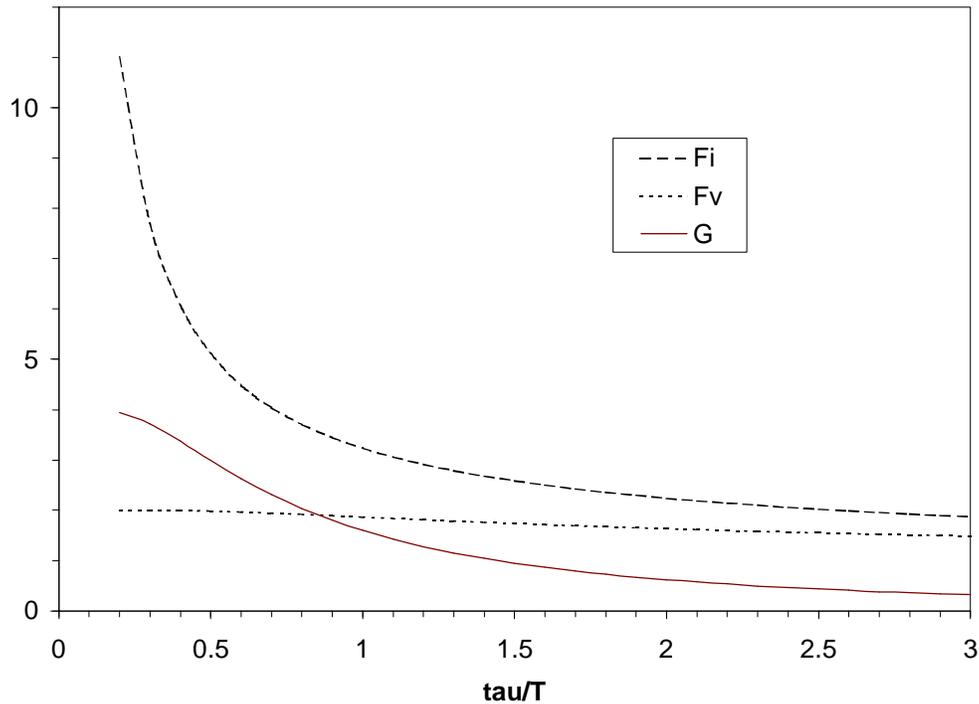
Parameters:  $T = 100 \text{ ns}$   
 $C_d = 10 \text{ pF}$   
 $v_n = 2.5 \text{ nV}/\sqrt{\text{Hz}}$   
 $\rightarrow i_n = 0.2 \text{ pA}/\sqrt{\text{Hz}} \quad (I_b = 100 \text{ nA})$



Noise attains minimum for  $\tau = 0.5 T$ .

### 3. Form Factors $F_i$ , $F_v$ and Signal Gain $G$ vs. $\tau / T$

Note: In this plot the form factors  $F_i$ ,  $F_v$  are not yet corrected by the gain  $G$ .



The voltage noise coefficient is practically independent of  $\tau / T$ .

Voltage contribution to noise charge dominated by  $C_i/\tau$ .

The current noise coefficient increases rapidly at small  $\tau / T$ .

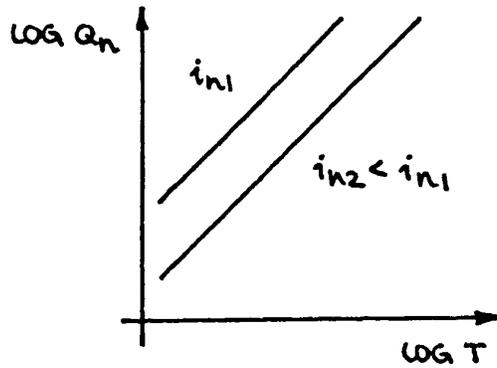
At large  $\tau / T$  the contribution to the noise charge increases because of  $\tau$  dependence.

The gain dependence increases the equivalent noise charge with increasing  $\tau / T$  (as the gain is in the denominator).

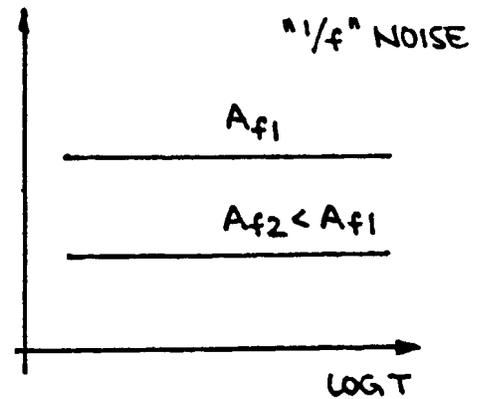
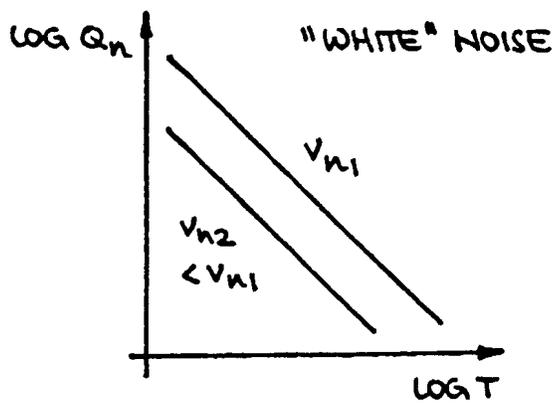


# 1. Equivalent Noise Charge vs. Pulse Width

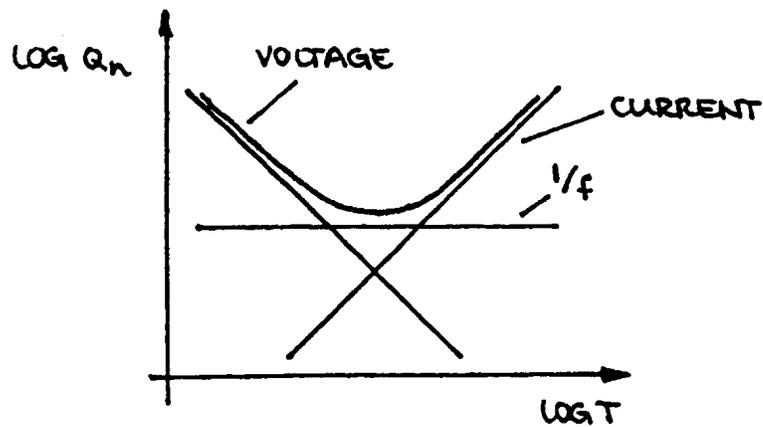
Current Noise vs. T



Voltage Noise vs. T



Total Equivalent Noise Charge



2. Equivalent Noise Charge vs. Detector Capacitance ( $C_i = C_d + C_a$ )

$$Q_n = \sqrt{i_n^2 F_i T + (C_d + C_a)^2 v_n^2 F_v \frac{1}{T}}$$

$$\frac{dQ_n}{dC_d} = \frac{2C_d v_n^2 F_v \frac{1}{T}}{\sqrt{i_n^2 F_i T + (C_d + C_a)^2 v_n^2 F_v \frac{1}{T}}}$$

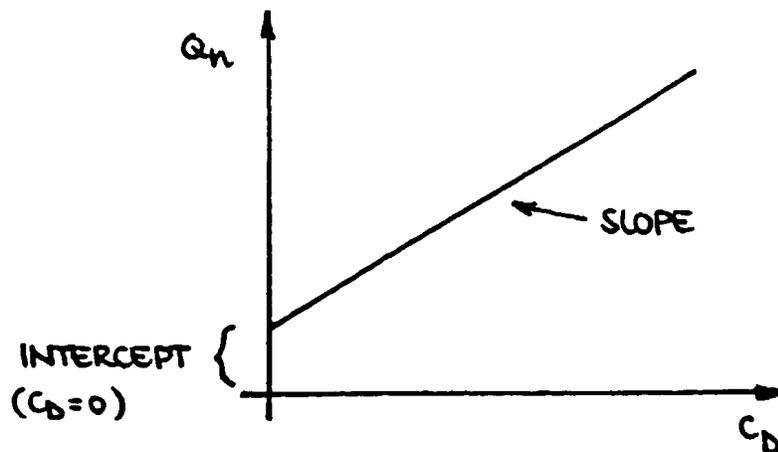
If current noise  $i_n^2 F_i T$  is negligible

$$\frac{dQ_n}{dC_d} \approx 2v_n \cdot \sqrt{\frac{F_v}{T}}$$

$\uparrow$                        $\uparrow$   
 input                      shaper  
 stage

Zero intercept

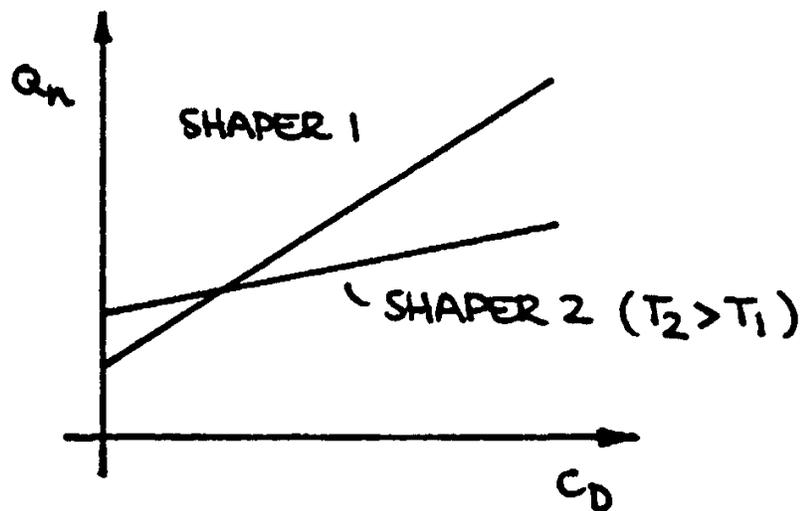
$$Q_n|_{C_d=0} = C_a v_n \sqrt{F_v / T}$$



Noise slope is a convenient measure to compare preamplifiers and predict noise over a range of capacitance.

Caution: both noise slope and zero intercept depend on both the preamplifier and the shaper

Same preamplifier, but different shapers:



Caution: Current noise contribution may be negligible at high detector capacitance, but not for  $C_d=0$ .

$$Q_n|_{C_d=0} = \sqrt{i_n^2 F_i T + C_a^2 v_n^2 F_v / T}$$