

The South Pole Telescope – Cosmology, Detectors, and Life at the Pole

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Outline

1. Physics Introduction

Brief Overview of Physics Goals

2. Measurement Techniques

Cosmic Microwave Background as a Tool

3. Detectors

Superconducting Transition Edge Sensors
+ Multiplexed Readout at 0.25K

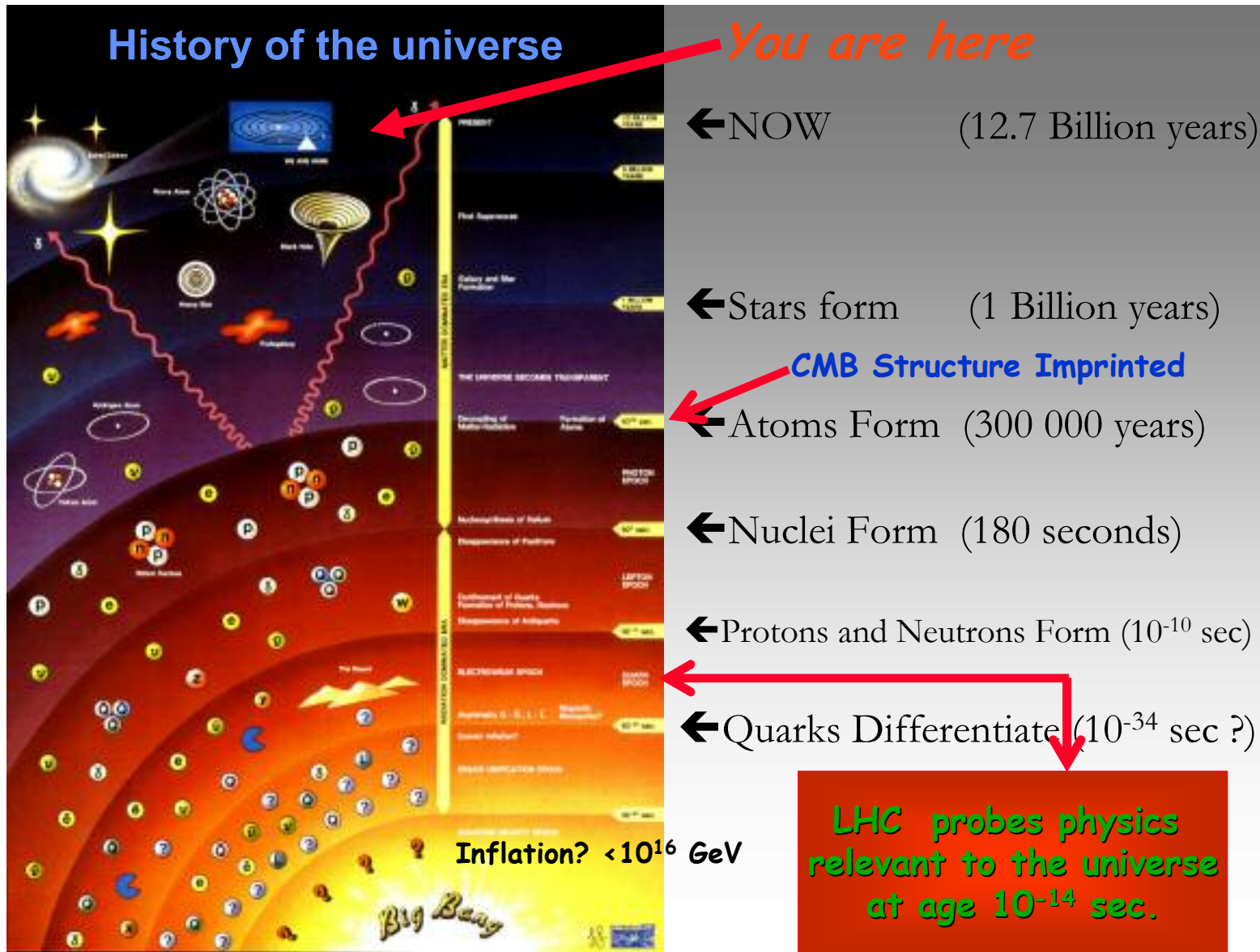
4. Life at the Pole

It's a nice place to work

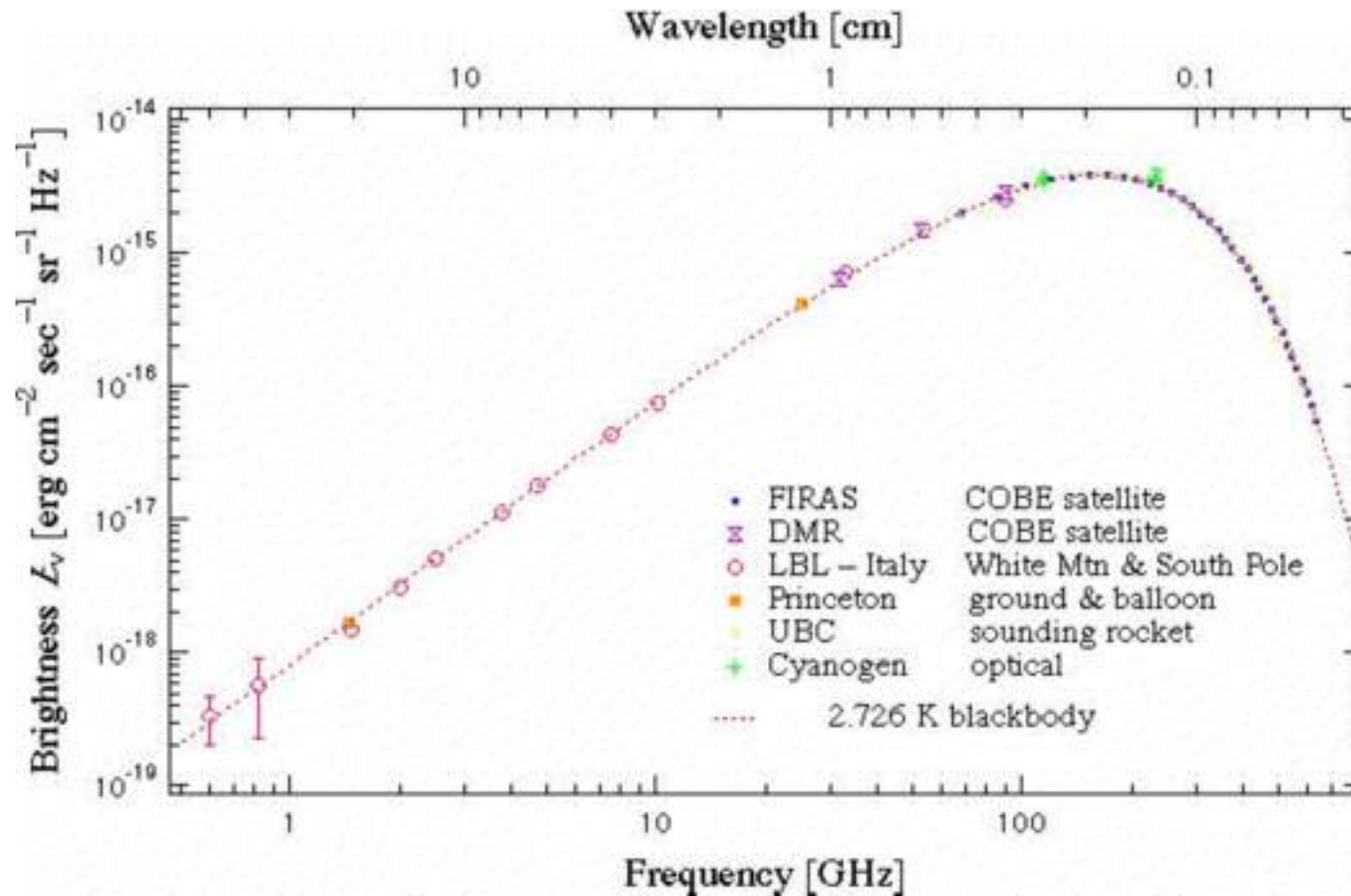
More information at spt.uchicago.edu

and

www-physics.LBL.gov/~spieler.



CMB has a near perfect black body spectrum ($T = 2.7\text{K}$)
 – measurements within 1% of theoretical spectrum

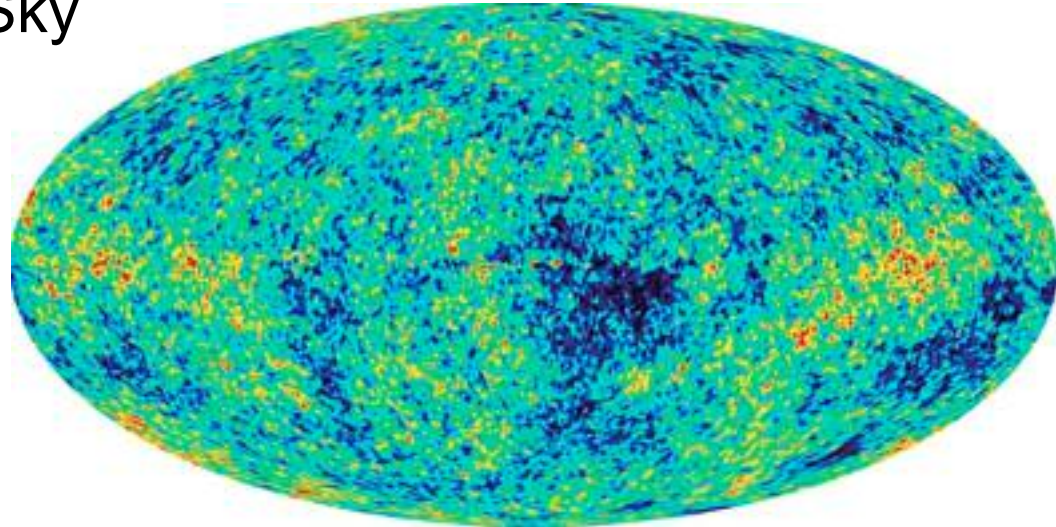


CMB very well understood –
 has provided precision data on key cosmological parameters.

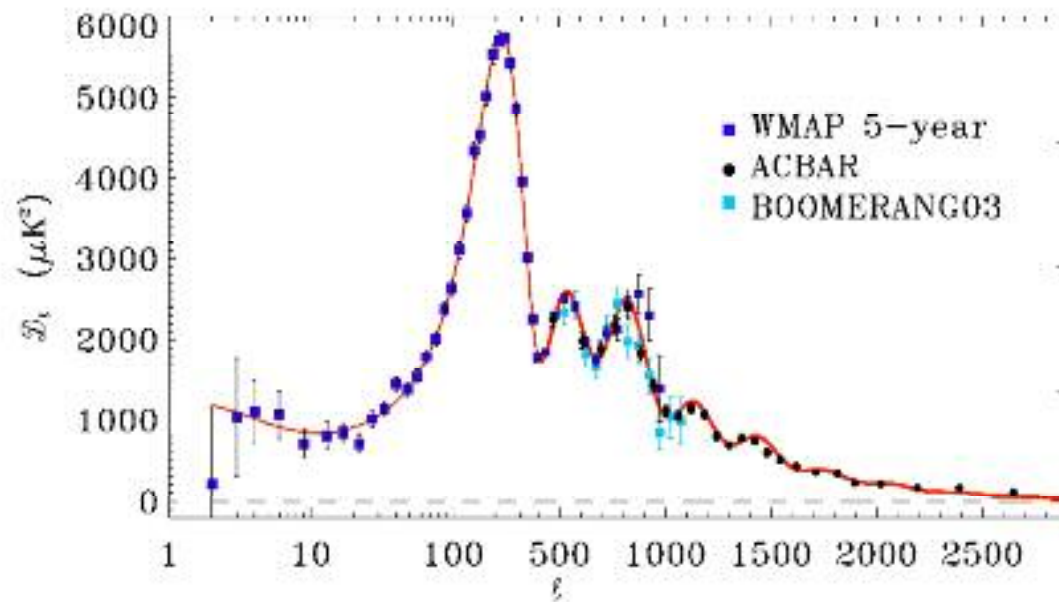
Map Temperature of Sky

Data from WMAP

Temperature anisotropy $\sim 10^{-5}$



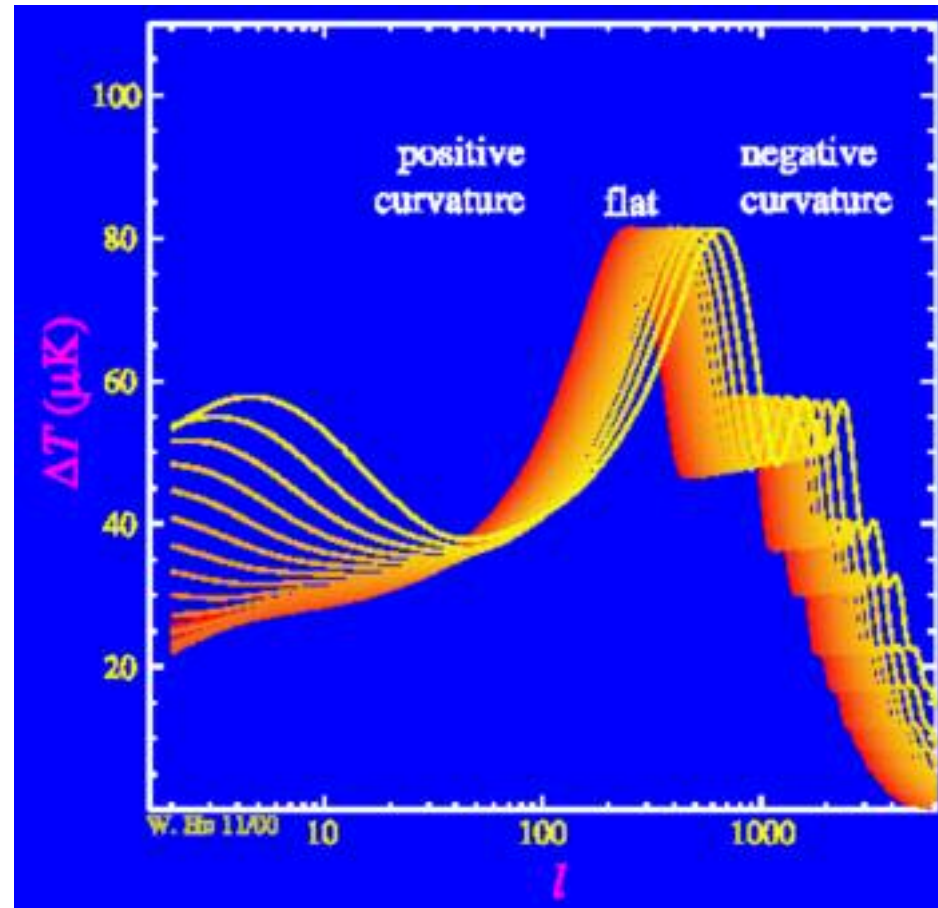
Angular distribution



Angular Scale $\Delta\Theta \approx 180/l$

Angular structure depends on cosmological parameters

For example, geometry:
 dominant angular scale $\sim 1^\circ$
 \Rightarrow universe is flat



Angular Scale $\Delta\Theta \approx 180/l$

Analyzing the power spectrum:

Normalization set by the total amount of matter $\Omega_M = \Omega_b + \Omega_{CDM}$

Position of 1st peak:
geometry of universe

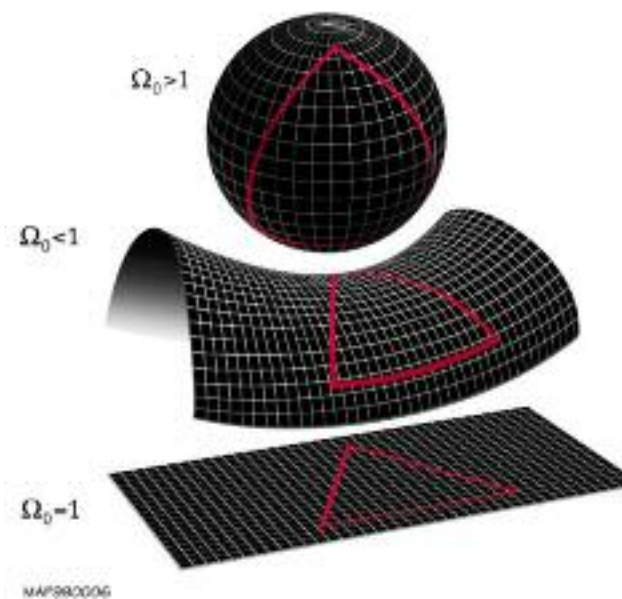
$l > 200$ $\Omega_0 > 1$ pos. curv.

$l \approx 200$ $\Omega_0 = 1$ flat

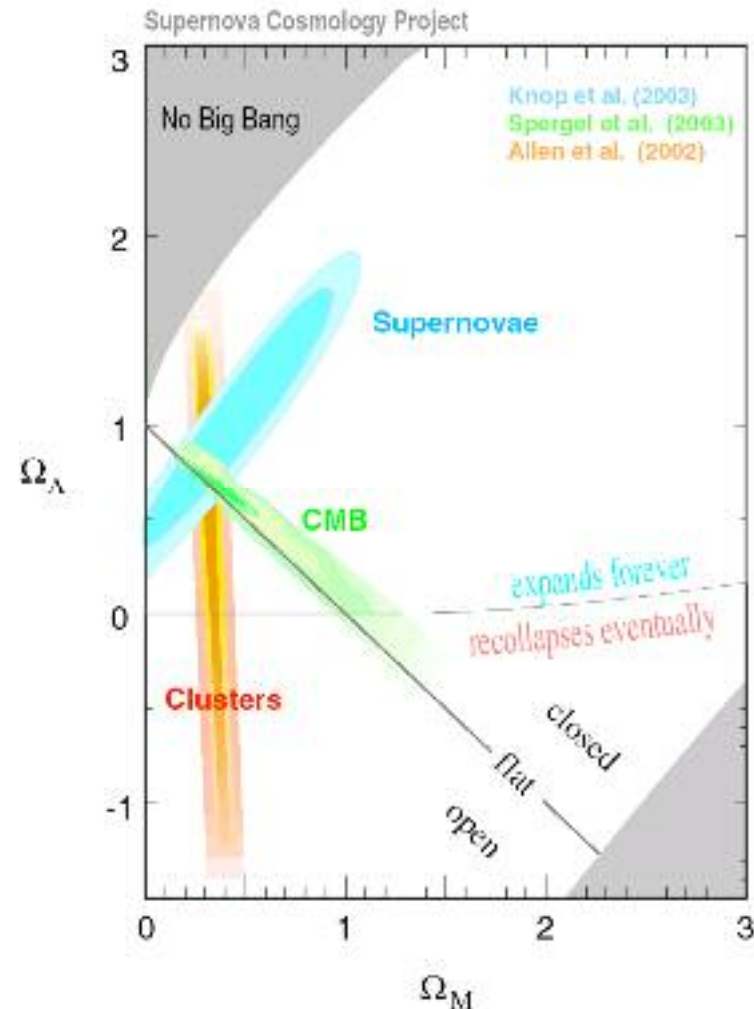
$l < 200$ $\Omega_0 < 1$ neg. curv.

Ratio of 1st to 2nd peak: amount of baryonic matter

3rd peak $>$ 2nd peak: presence of cold dark matter



- CMB measurements provide constraints on fundamental cosmological parameters
- CMB spatial distribution largely unaffected since 300k yrs after Big Bang
- Supernova and CMB data *together* give best constraints on mass and energy density of the universe
- Also consistent with Ω_m from Large Scale Structure data



Cosmology relies on combined data from different techniques

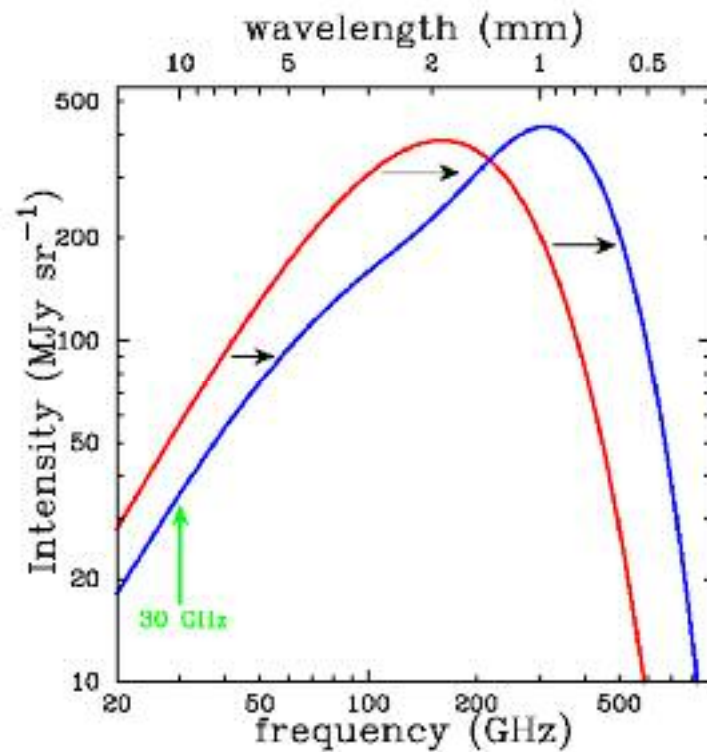
Today we use CMB as a tool:

Example: Map large-scale structure using Sunyaev-Zel'dovich Effect to measure density of galaxy clusters vs red shift $\Rightarrow w, \Omega_m$ (gravity vs. "dark energy")

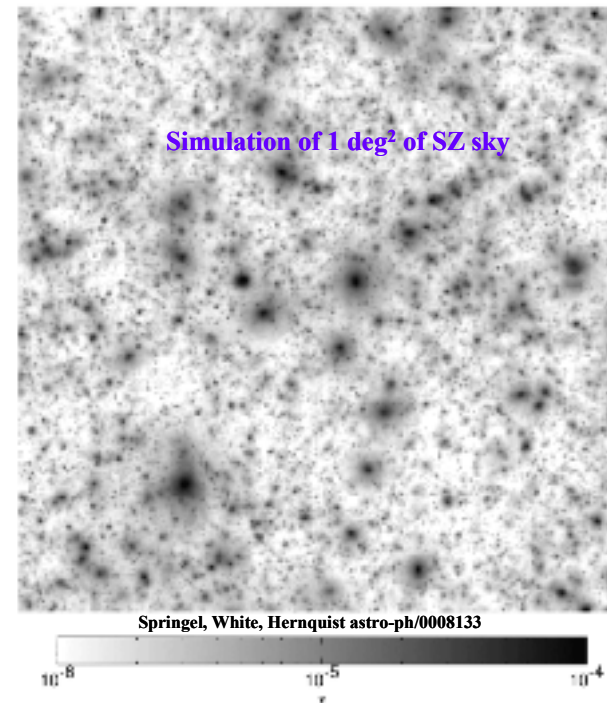
Inverse Compton scattering: Hot gas bound to clusters of galaxies scatters CMB

\Rightarrow distorts black-body spectrum – shifts to higher frequencies:

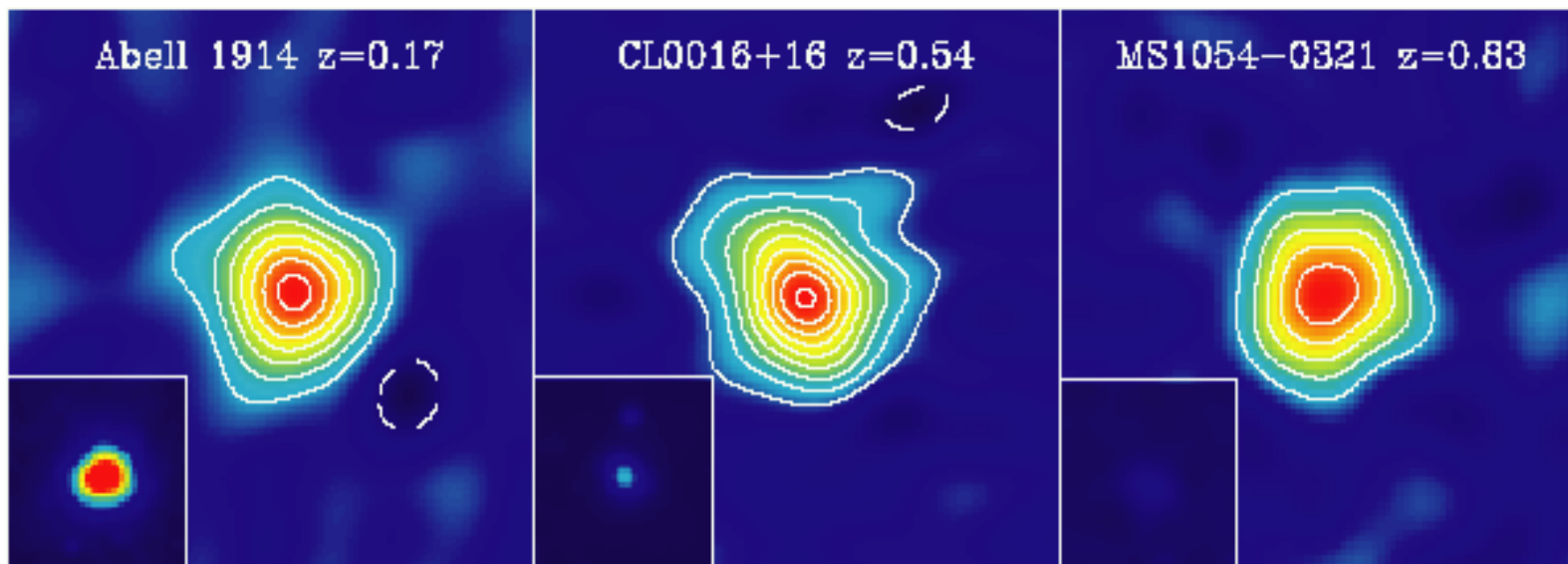
At 150 GHz clusters appear as dark spots



Galaxy cluster searches



SZ signal independent of redshift z



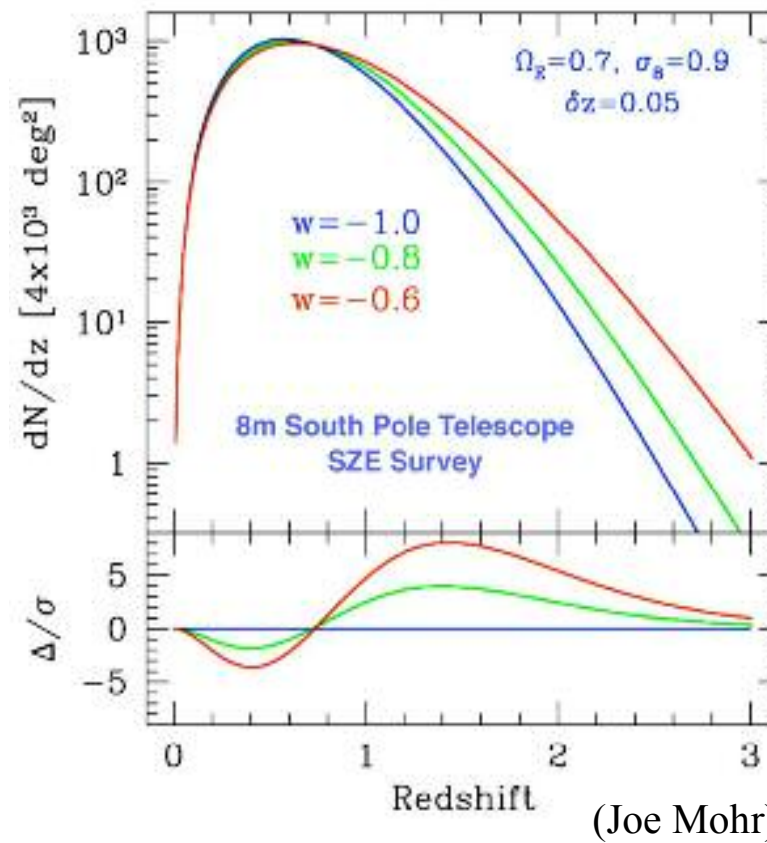
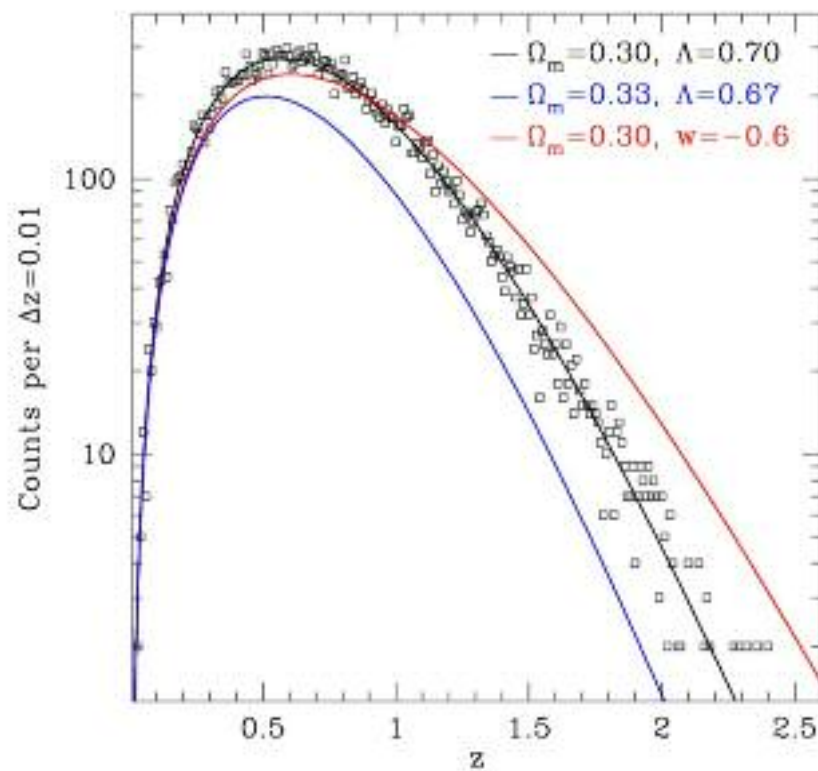
(Holzapfel et al.)

In contrast to x-rays (insets), SZ surface brightness is independent of redshift, so clusters can be seen at any distance.

However, optical data needed to determine redshift (collaboration with DES and others)

Technique that requires arrays with high sensitivity to achieve efficiency in random searches.

Cluster densities at $z > 1$ sensitive to cosmological parameters



w is the equation of state parameter for Dark Energy

Other SPT Cosmology Studies

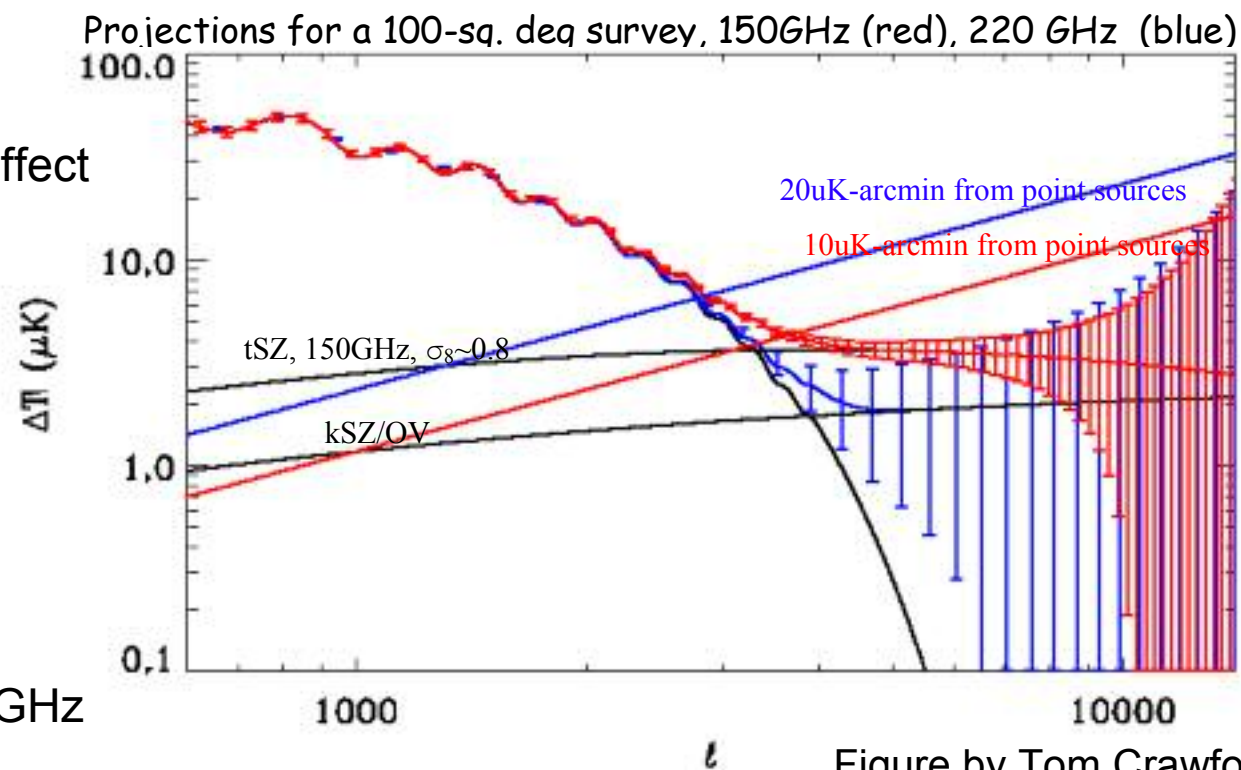
1. Foregrounds / Point Sources

Foregrounds include active galactic nuclei (AGN) and dust emission from galaxies

2. Thermal Sunyaev-Zel'dovich Effect

CMB spectrum can be distorted by scattering off of free electrons

⇒ "Energy kick" in galaxy clusters dominates power spectrum at 150 GHz for $l > 2500$

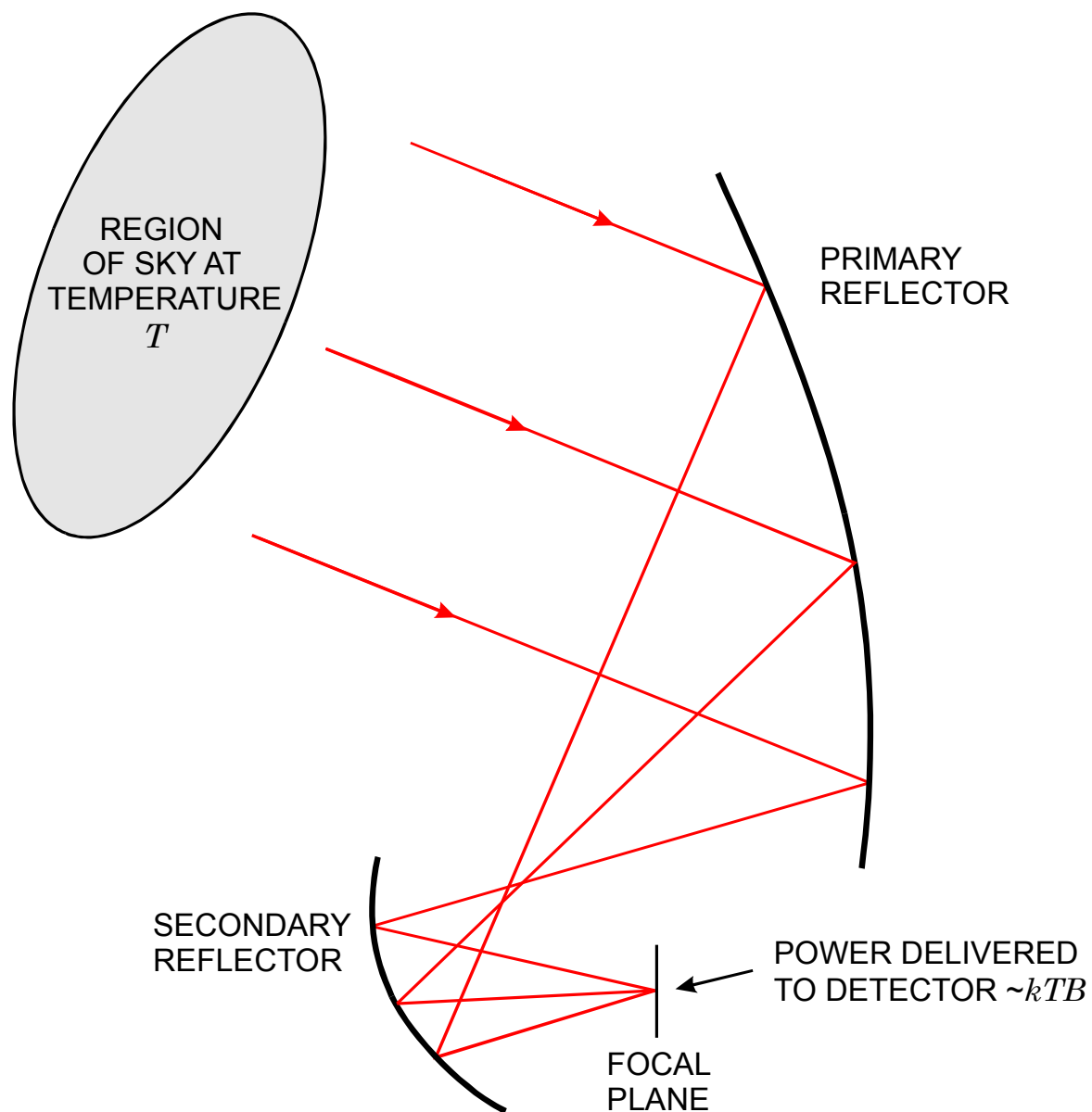


Good measurement of σ_8 – amplitude of initial density perturbations.

DETECTORS

Detected Signal

- View region of sky with temperature T (CMB: $T \approx 3\text{K}$)
- Measured signal proportional to kTB (B = bandwidth)



South Pole Telescope

10m diameter parabolic reflector
with off-axis feed

~25 micron surface accuracy

Beamwidth: 1.3 arcmin

1 deg field of view

Maximum scan speed: 4 deg/s

100% observing time

9300 ft altitude

Funded by NSF Polar Programs

First light 2007 – currently in
3rd year of observations



Why go the South Pole?

High altitude to reduce atmospheric absorption

Atmospheric absorption at the relevant frequencies depends strongly on water content

⇒ Site must be high and dry

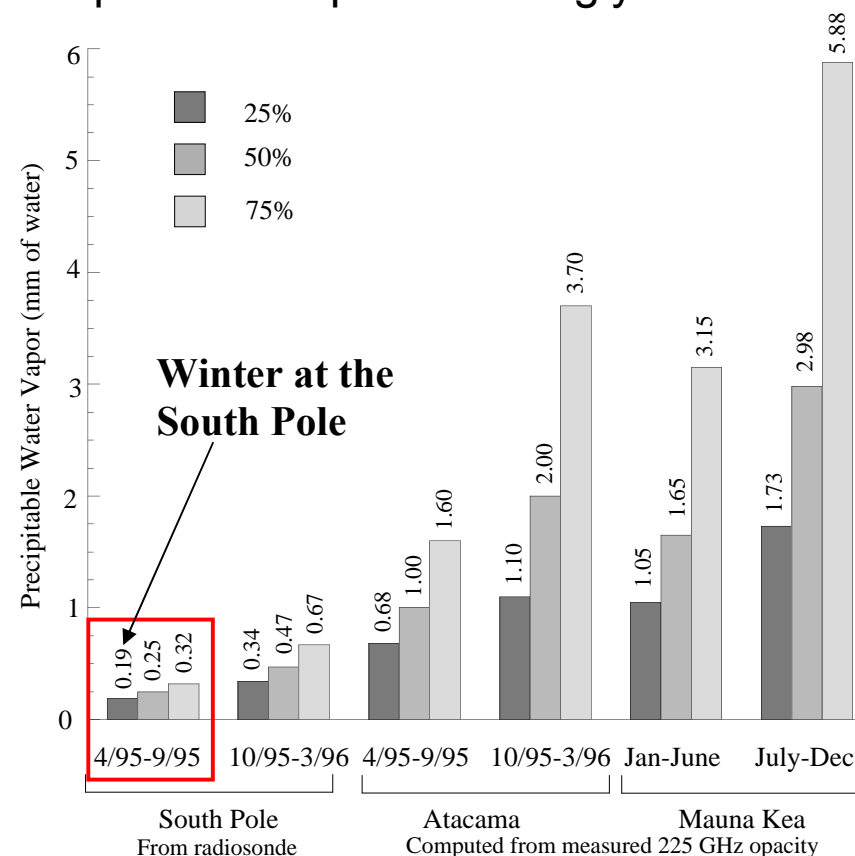
Atmospheric stability:
Antarctic winds go around the Pole

Good place to work

Other sites, e.g. Atacama Plateau in Chile are also good.

Although precipitation is higher and more atmospheric variations, there is greater flexibility in scanning strategies.

To reduce systematic errors, scans of a given portion of the sky should be performed with various scan orientations.



SPT Collaboration

UC Berkeley

William Holzapfel
 Adrian Lee
 Christian Reichardt
 Bradford Benson
 Martin Lueker
 Jared Mehl
 Tom Plagge
 Dan Schwan
 Erik Shirokoff

LBNL

Helmuth Spieler

Case Western Reserve University

John Ruhl
 Tom Montroy
 Zak Staniszewski

University of Chicago

John Carlstrom (P.I.)
 Steve Padin (Proj. Manager)
 Stephan Meyer
 Clem Pryke
 Tom Crawford
 Jeff McMahon
 Clarence Chang
 Kathryn Schaffer
 Joaquin Vieira
 Ryan Keisler
 Lindsey Bleem
 Abigail Crites
 Erik Leitch

Harvard-Smithsonian Center for Astrophysics

Tony Stark

University of Colorado

Nils Halverson

NIST

Hsiao-Mei (Sherry) Cho

McGill

Matt Dobbs
 Gil Holder

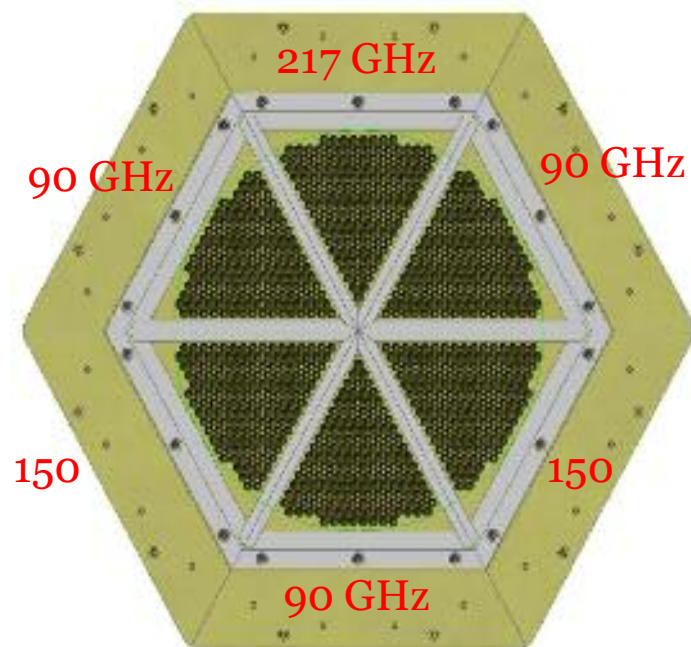
Univ. of Illinois Urbana

Joe Mohr

UC Davis

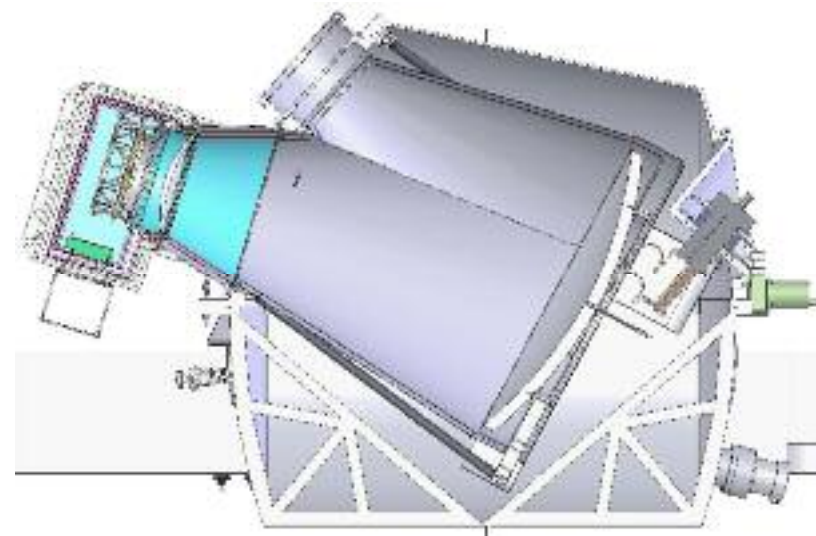
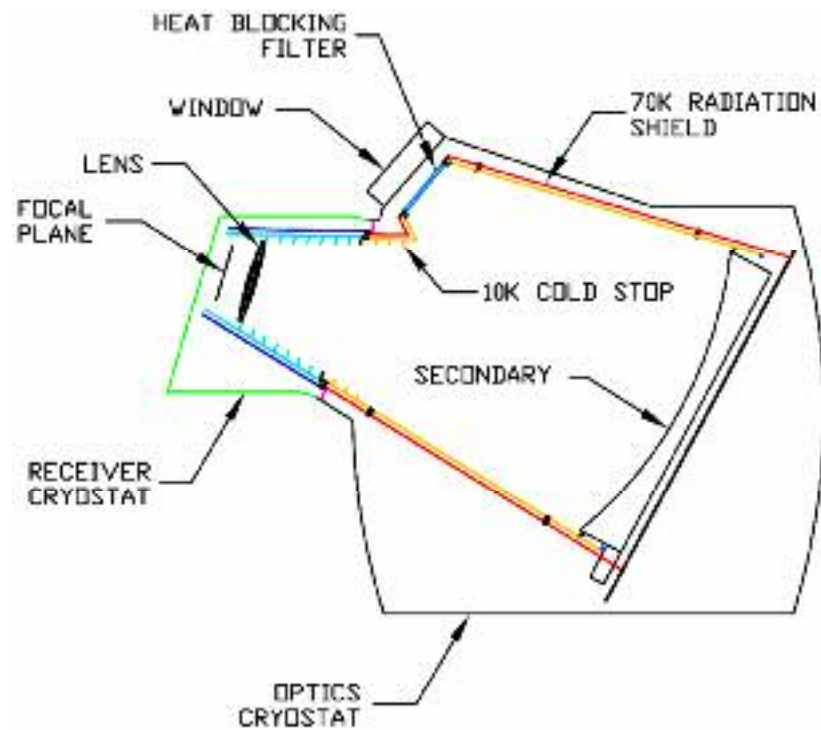
Lloyd Knox
 Jason Dick

Optics and Focal Plane



Current configuration:

4 wedges at 150 GHz
1 ea. at 90 and 220 GHz



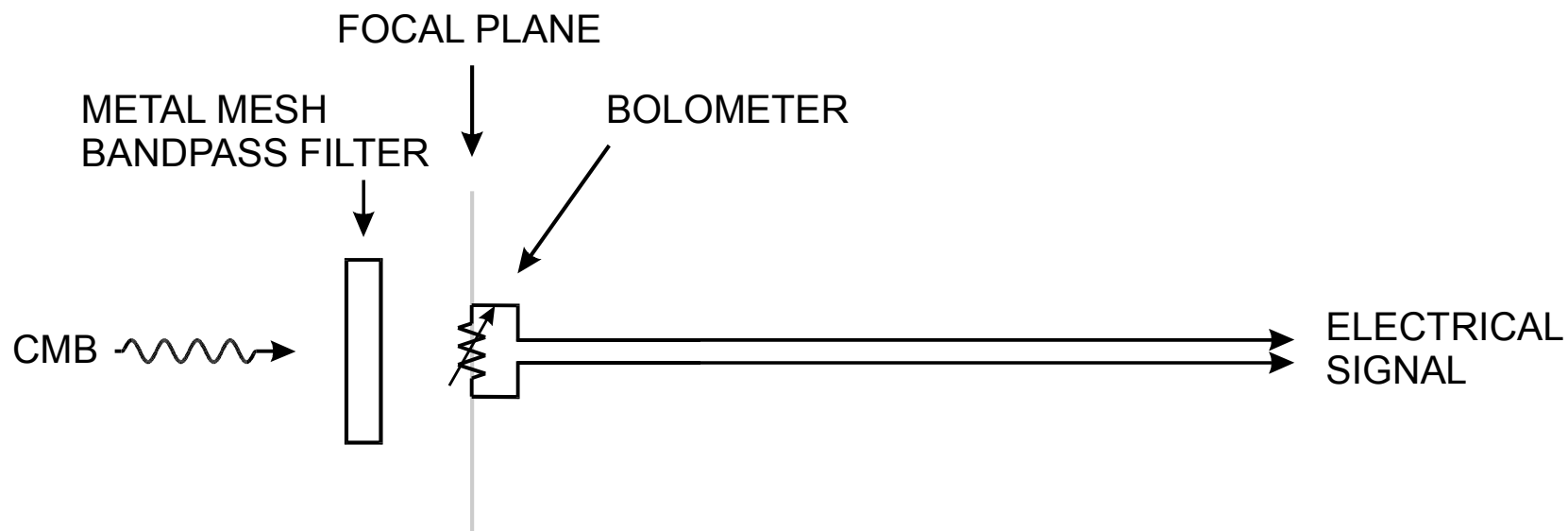
Signals are measured with bolometers

The signal is thermal noise ($T = 2.7\text{K}$):

$$P = kTB = 2.2 \cdot 10^{-15} B \text{ erg/Hz (or } 2.3 \cdot 10^{-4} B \text{ eV/Hz)}$$

B = Bandwidth

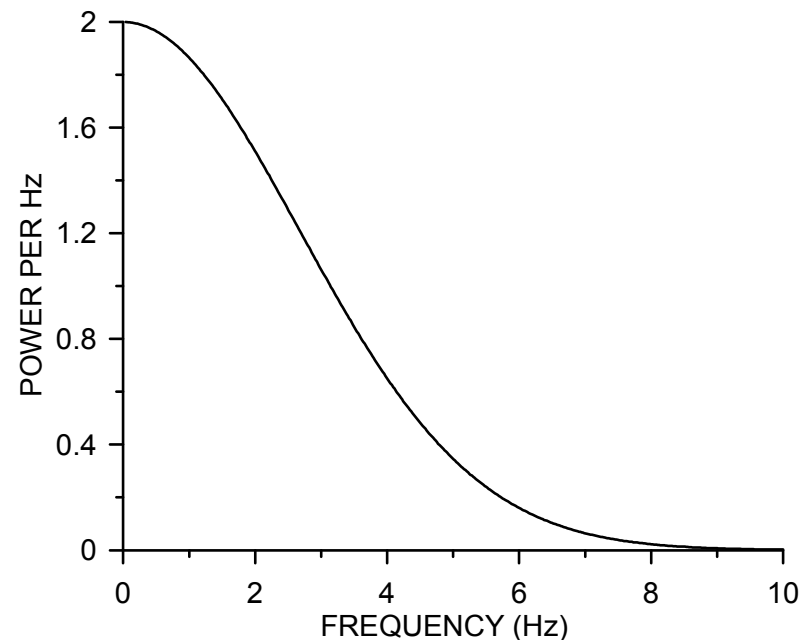
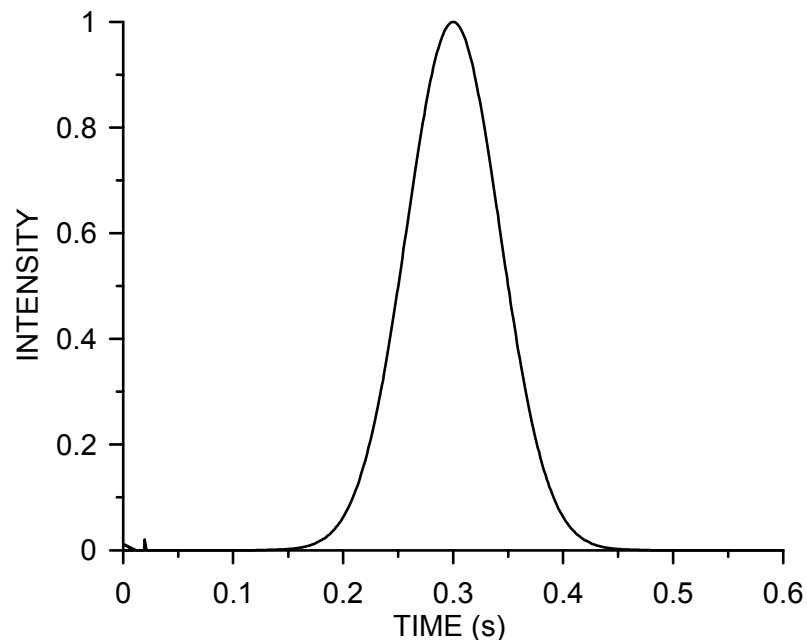
Cluster signal $< 1 \text{ mK}$



Signal Spectrum in Galaxy Cluster Search

Antenna beam width: 1' FWHM

Scan speed: 10'/s



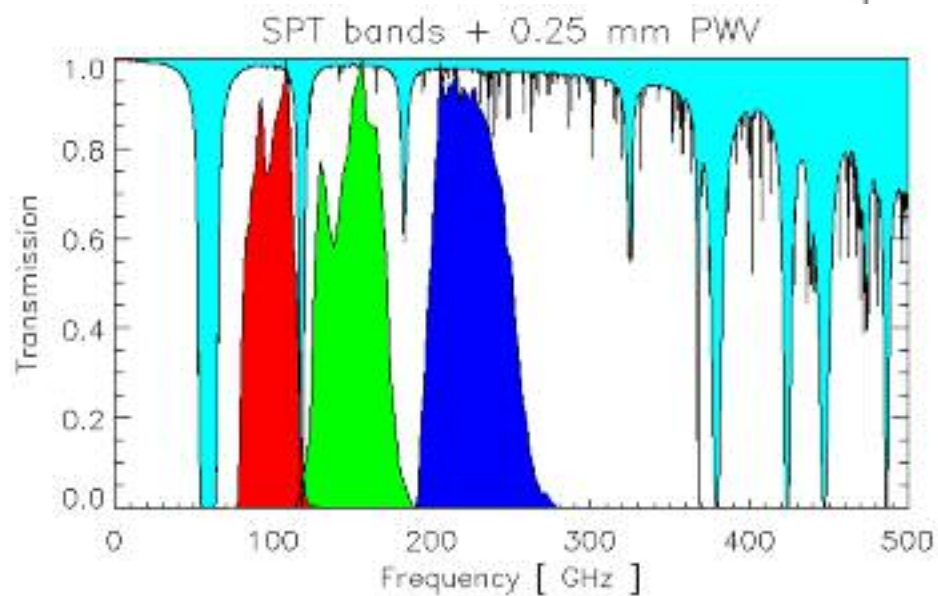
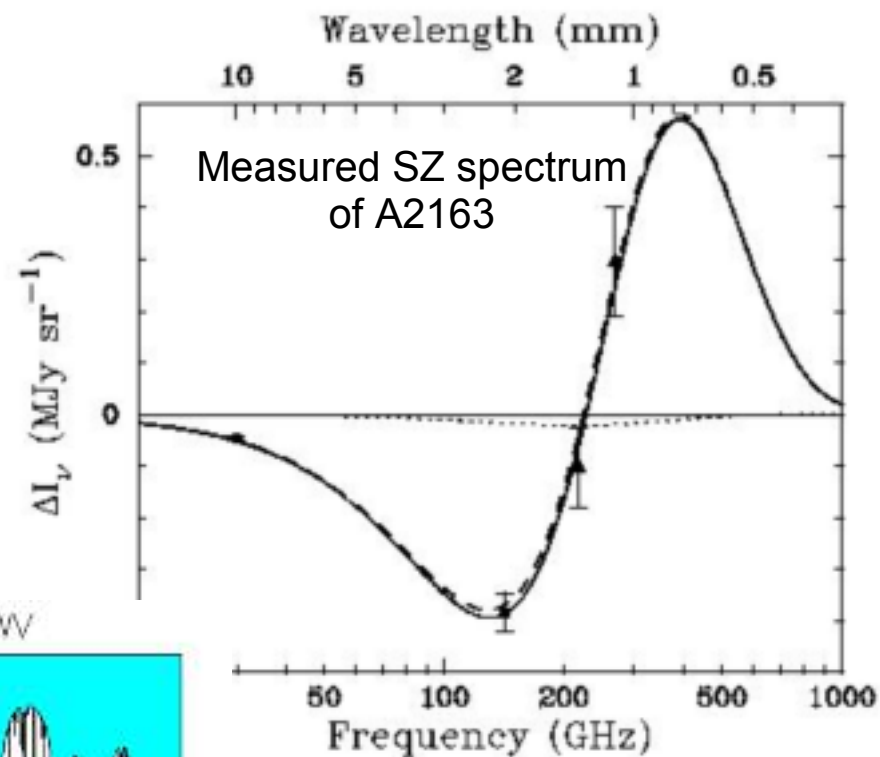
(W. Lu, CWRU)

Typical observations: scan back and forth in azimuth at 0.25 degrees/s,
step in elevation

⇒ Maintain Gain Stability + Noise Level down to ~0.1 Hz

SZ Effect

Observing Bands:
90, 150, 220 GHz



New Experiments require a major step up in sensitivity

Bolometers today are so sensitive that we are limited by the shot noise of the CMB photons

Increase sensitivity by

performing many measurements simultaneously

⇒ bolometer arrays (100s to 1000s)

extending observation time

⇒ ground-based experiments
eventually space-based

Bolometer array technology:

Wafer-scale monolithic fabrication (“radiometer on a chip”)

Cold multiplexing on 0.25K stage (reduce heat leaks through wiring)

Cryogen free system: pulse tube cooler + $^4\text{He}/^3\text{He}/^3\text{He}$ sorption fridge
(remote operation with minimal on-site staff)

Berkeley Bolometer Group

William Holzapfel (UCB)

Adrian Lee (LBNL,UCB)

Paul Richards (UCB)

Helmuth Spieler (LBNL)

John Clarke (LBNL,UCB) SQUIDs

Greg Engargiola (UCB RAL)

John Joseph (Eng. Div. LBNL)

Chinh Vu (Eng. Div. LBNL)

Brad Benson (UCB – now Univ. Chicago)

H.-M. “Sherry” Cho (UCB – now NIST)

Matt Dobbs (LBNL

– now McGill Univ.)

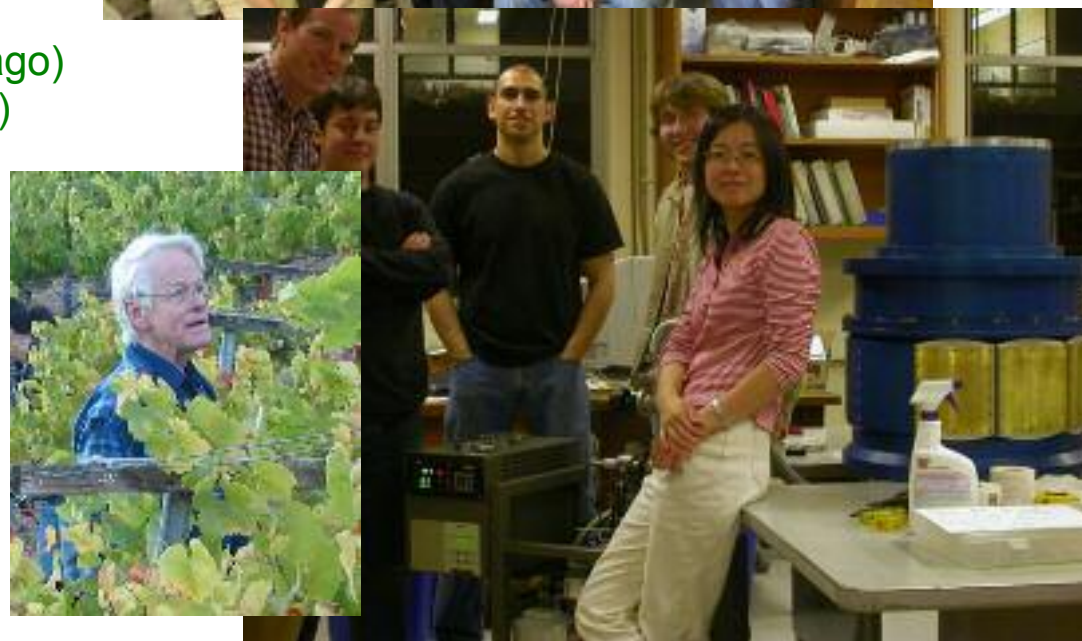
Nils Halverson (UCB

– now Univ. Colorado)

Huan Tran (UCB)

+ 15 graduate students

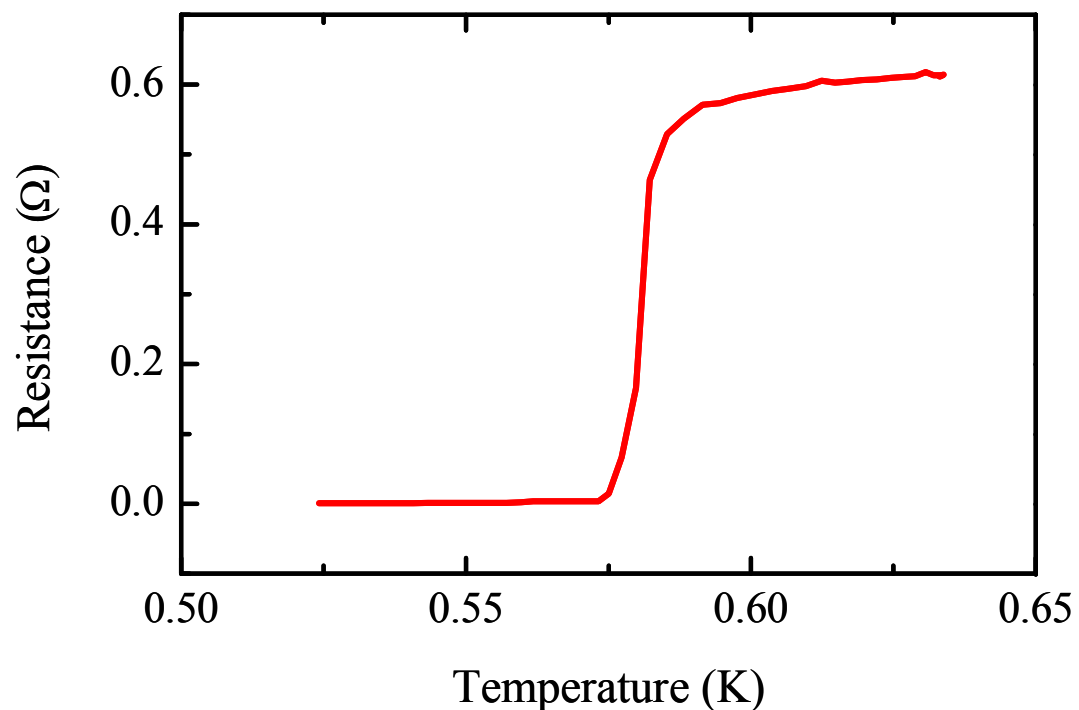
Support: NSF, NASA, DoE



Bolometers

Superconducting transition edge sensors:

- Bias thin film superconductor at transition from super- to normal conducting
⇒ Large change in resistance with absorbed power



- Thin bi-layers (e.g. Al – Ti) allow tuning of transition temperature

Why Bolometers?

Amplifiers (phase coherent systems) subject to quantum noise limit.

Minimum spectral noise power density: $\frac{dP}{d\omega} = \hbar\omega$

Follows from uncertainty principle.

(H.A. Haus and J.A. Mullen, Phys. Rev. 128 (1962) 2407-2413)

For a simple derivation see Spieler, *Semiconductor Detector Systems*, pp. 132-133

Bolometers do not preserve phase, so not subject to quantum noise limit.

Thermal Detectors

Basic principle:

Assume thermal equilibrium:

If all absorbed Energy $E = \Phi \Delta t$ is converted into phonons, the temperature of the sample will increase by

$$\Delta T = \frac{E}{C},$$

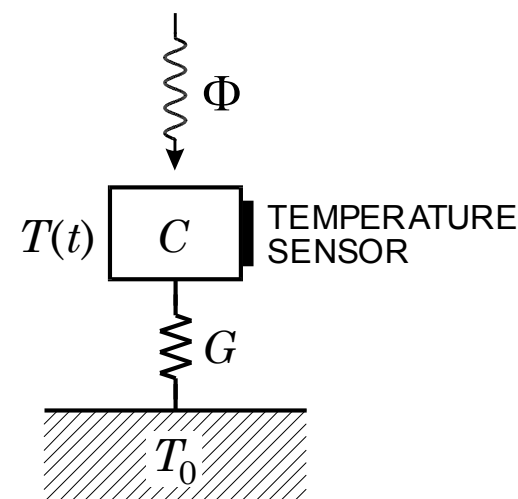
where C is the heat capacity of the sample (specific heat x mass).

After absorption of an energy packet E the heat flows through the thermal conductance G and the bolometer temperature decays as

$$T - T_0 = \frac{E}{C} e^{-t/\tau}$$

with the thermal time constant $\tau = \frac{C}{G}$,

analogous to a capacitor discharged through a resistance.



Voltage-Biased Transition-Edge Sensors

Required power is of order pW, i.e. voltage of order μV
 current of order μA

Simplest to bias device with a constant current and measure change in voltage

Problem: power dissipated in sensor $P = I^2 R$

Increasing $R \Rightarrow$ Increasing $P \Rightarrow$ Increasing $R \Rightarrow$ Increasing P

\Rightarrow thermal runaway

When biased with a constant voltage $P = \frac{V_b^2}{R}$

Increasing $R \Rightarrow$ Decreasing $P \Rightarrow$ Decreasing $T \Rightarrow$ Decreasing R

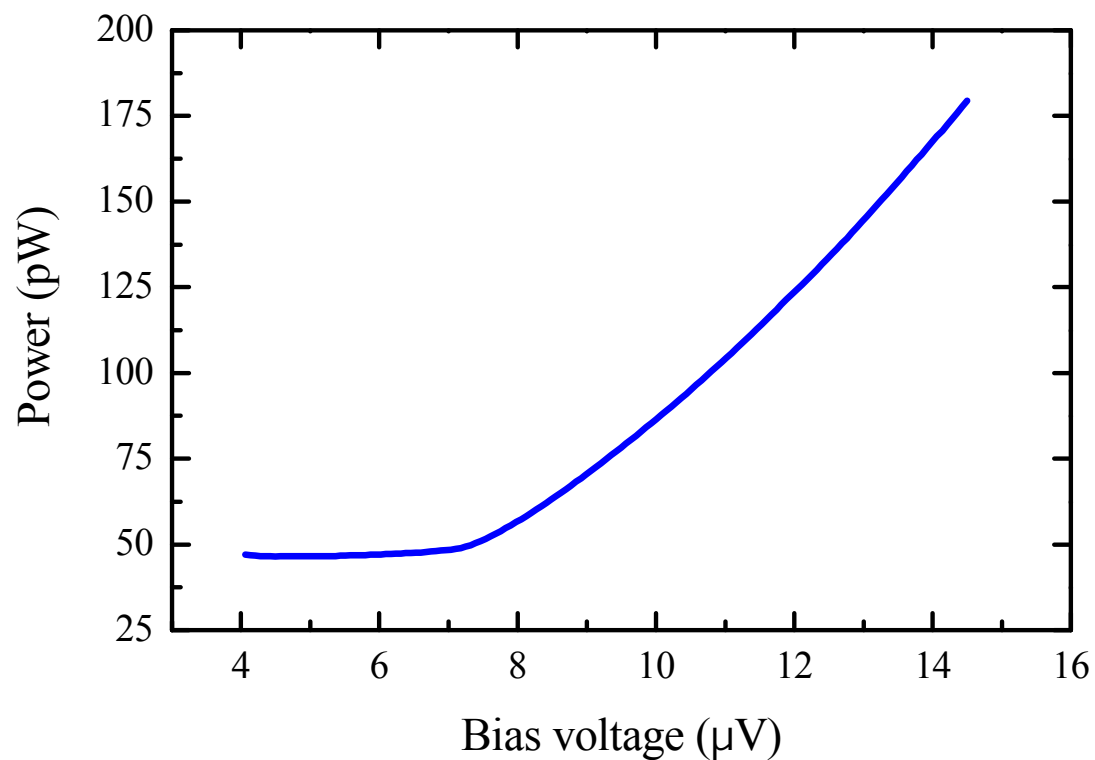
\Rightarrow negative feedback \Rightarrow stabilizes operating point

Analogous to op-amp: Bolometer time constant corresponds to amplifier cutoff frequency.

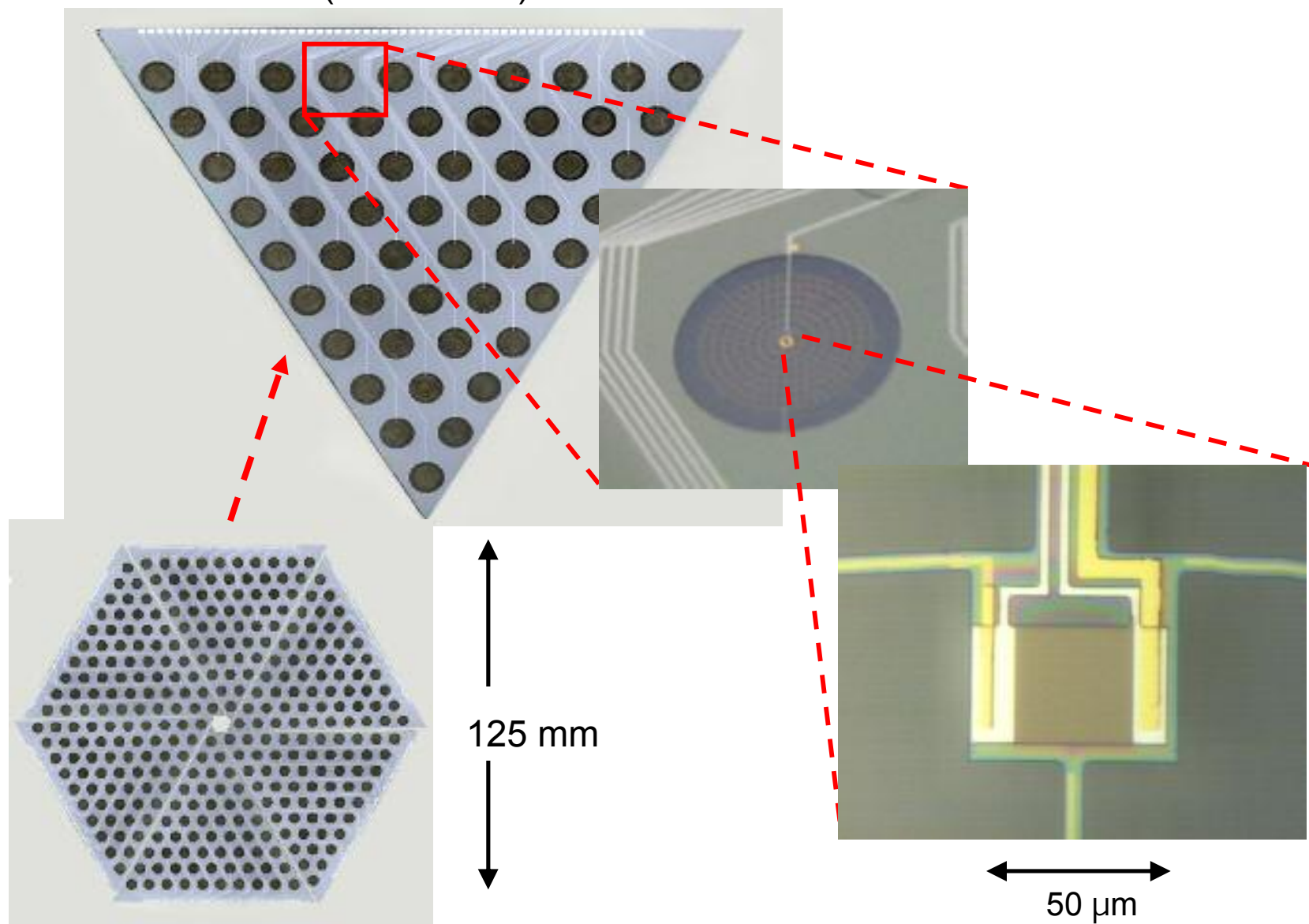
However, subject to constraints of feedback theory and possible instability!

- Operate with constant voltage bias
 - ⇒ Electrothermal negative feedback
 - ⇒ Stabilize operating point + predictable response
 - ⇒ “Constant power operation”:
Change in absorbed power is balanced by change in electrical power:

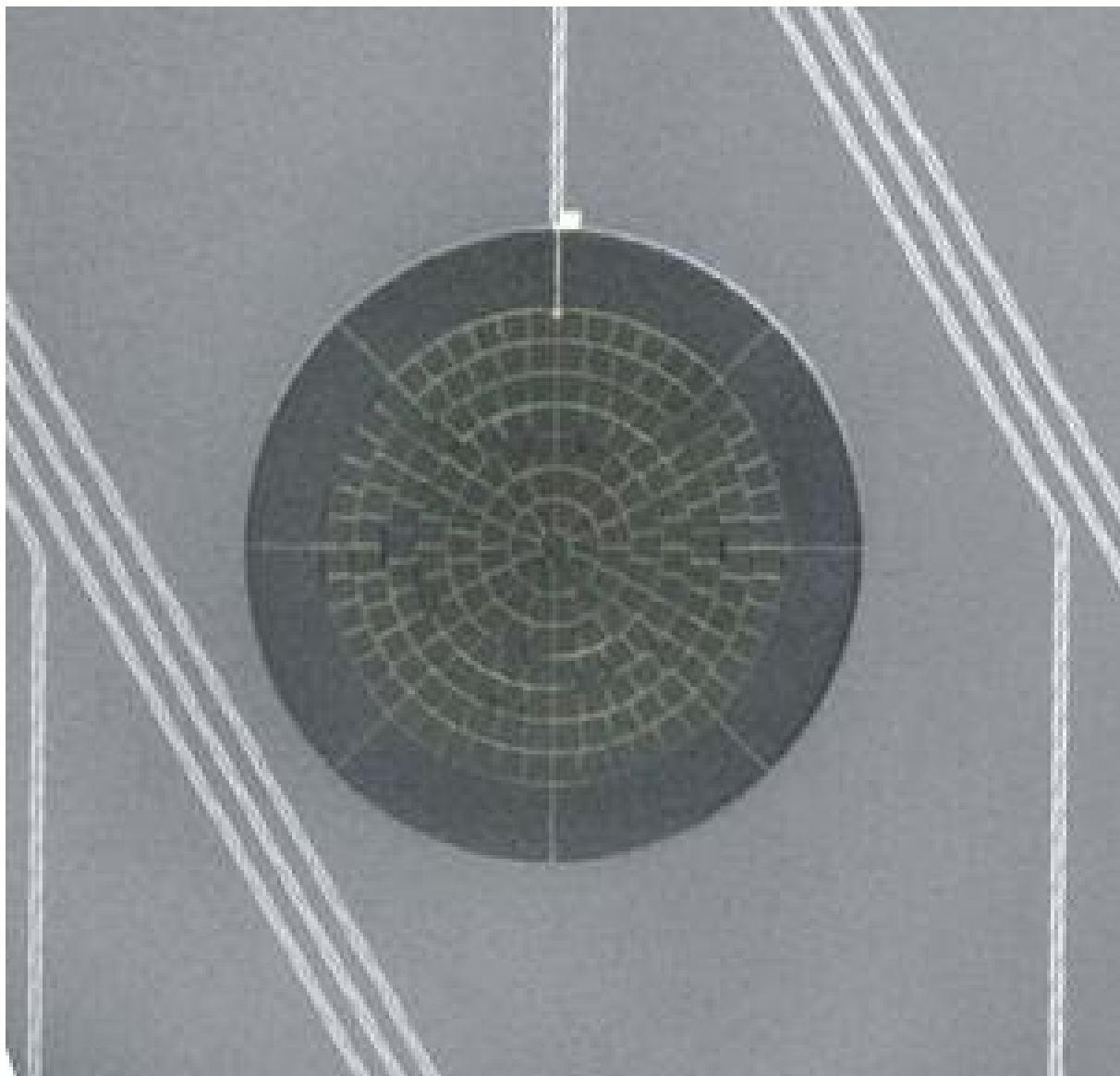
$$\Delta I / \Delta P = 1 / V_{bias}$$



APEX Focal Plane (Jared Mehl)



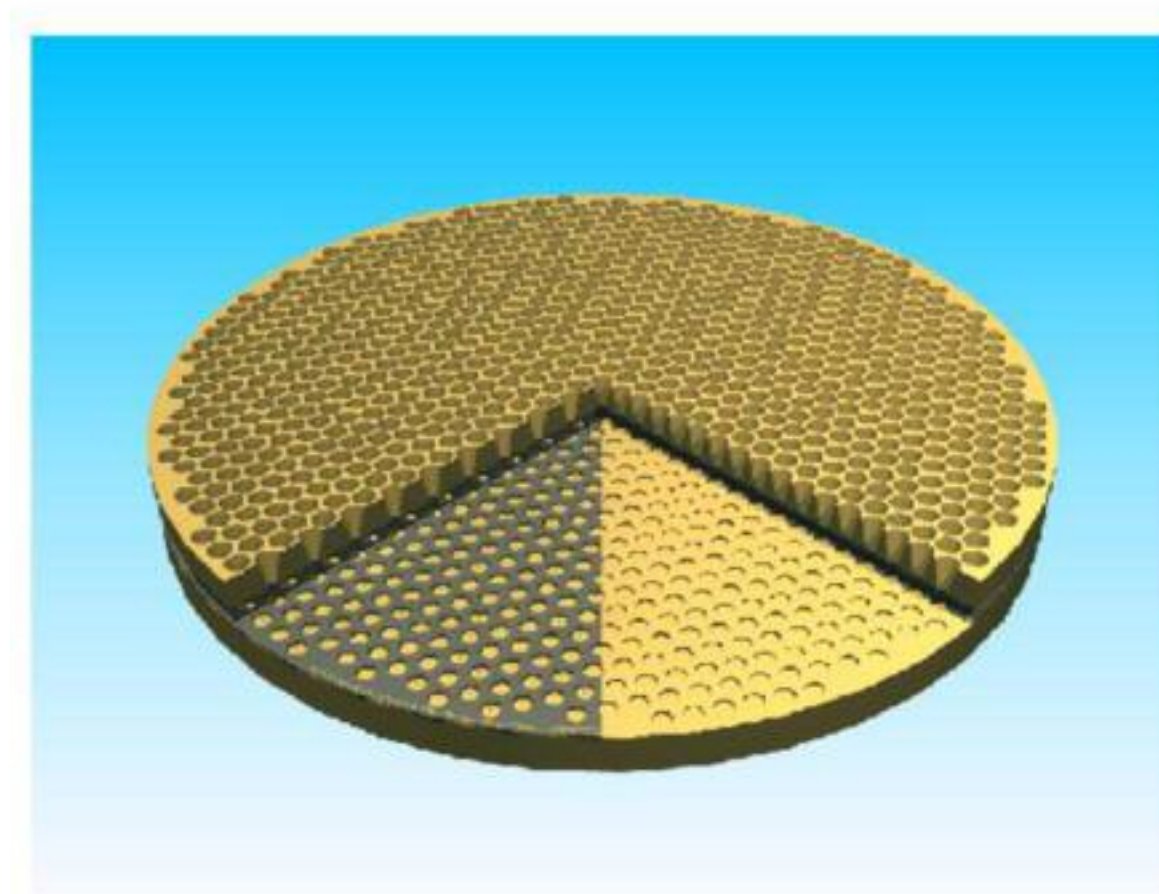
Close-up of spiderweb bolometer



Focal Plane Design for APEX-SZ and SPT

Disk with machined
conical horns
positioned above
bolometer array.

Horns match optics
to bolometer plane.



READOUT

- Constant voltage bias requires that readout impedance \ll bolometer resistance
 - bolometer resistance $\approx 1 \Omega$
 - bias resistance $\approx 20 \text{ m}\Omega$
 - amplifier input impedance $\approx 10 \text{ m}\Omega$
 - 1st amplifier stage: SQUID at 4K in shunt feedback configuration.
High-frequency feedback loop includes SQUID + warm electronics (300K).
- Typical bolometer bias power: 10 – 40 pW
(orders of magnitude greater than signal)
- Power Budget on 0.25K stage: $<10 \mu\text{W}$
- Heat conduction through wires to 4K stage acceptable up to ~ 300 bolometers
 - \Rightarrow Larger arrays require multiplexing
- Novel development:
 - Frequency-Domain MUX with ZERO additional power on cold stage
 - + no noise degradation

Principle of Frequency-Domain Multiplexing

1. High-frequency bias (~ 100 kHz – 1 MHz)

Each bolometer biased at different frequency

2. Signals change sensor resistance

⇒ Modulate current

⇒ Transfer signal spectrum to sidebands adjacent to bias frequency

⇒ Each sensor signal translated to unique frequency band

3. Combine all signals in common readout line

4. Retrieve individual signals in bank of frequency-selective demodulators

⇒ High-frequency bias greatly reduces sensitivity to microphonics!

Modulation Basics

If a sinusoidal current $I_0 \sin \omega_0 t$ is amplitude modulated by a second sine wave $I_m \sin \omega_m t$

$$I(t) = (I_0 + I_m \sin \omega_m t) \sin \omega_0 t$$

$$I(t) = I_0 \sin \omega_0 t + I_m \sin \omega_m t \sin \omega_0 t$$

Using the trigonometric identity $2 \sin \alpha \sin \beta = \cos(\alpha - \beta) - \cos(\alpha + \beta)$ this can be rewritten

$$I(t) = I_0 \sin \omega_0 t + \frac{I_m}{2} \cos(\omega_0 t - \omega_m t) - \frac{I_m}{2} \cos(\omega_0 t + \omega_m t)$$

The modulation frequency is translated into two sideband frequencies

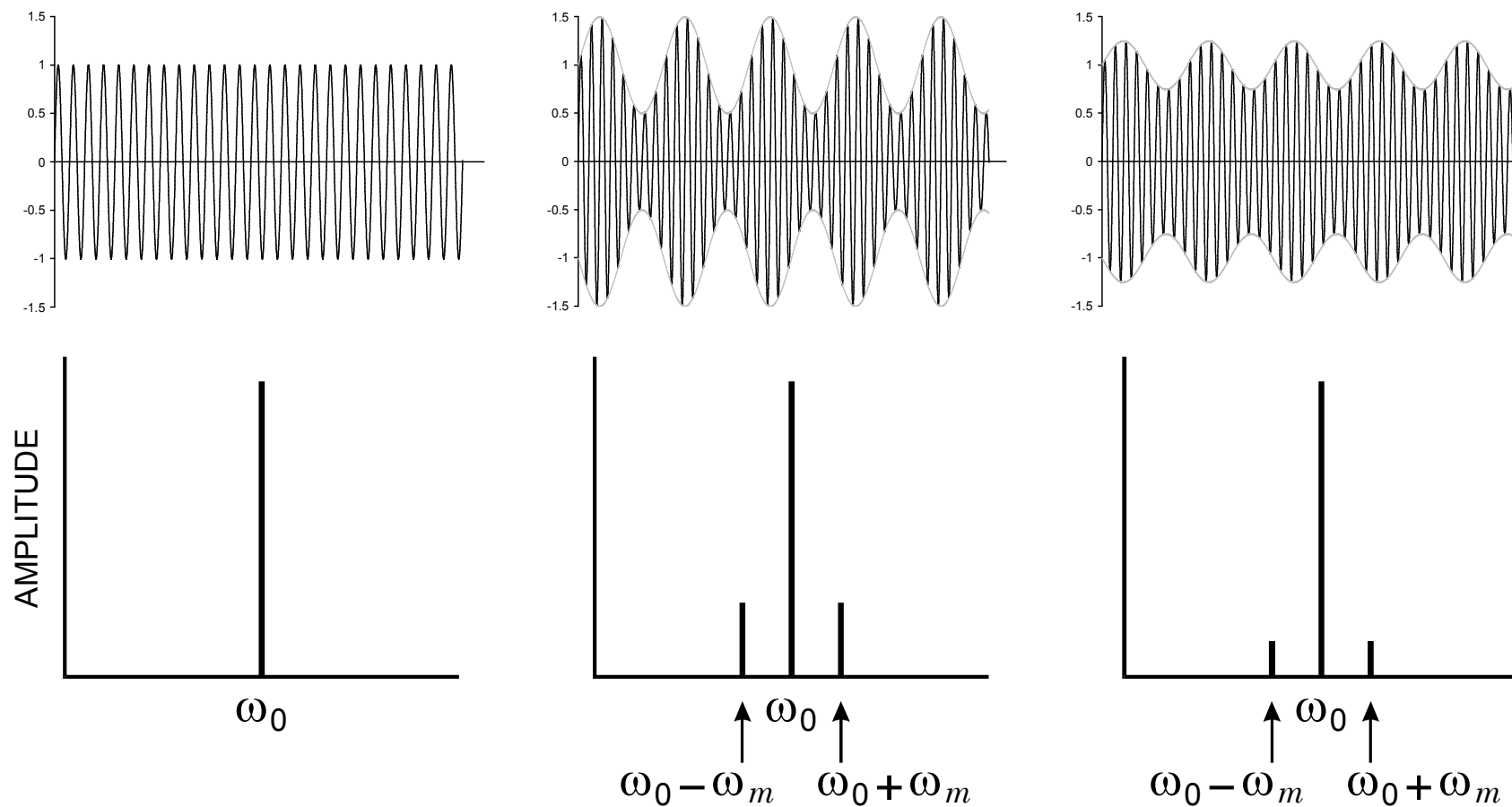
$$(\omega_0 t + \omega_m t) \text{ and } (\omega_0 t - \omega_m t)$$

symmetrically positioned above and below the carrier frequency ω_0 .

All of the information contained in the modulation signal appears in the sidebands; the carrier does not carry any information whatsoever.

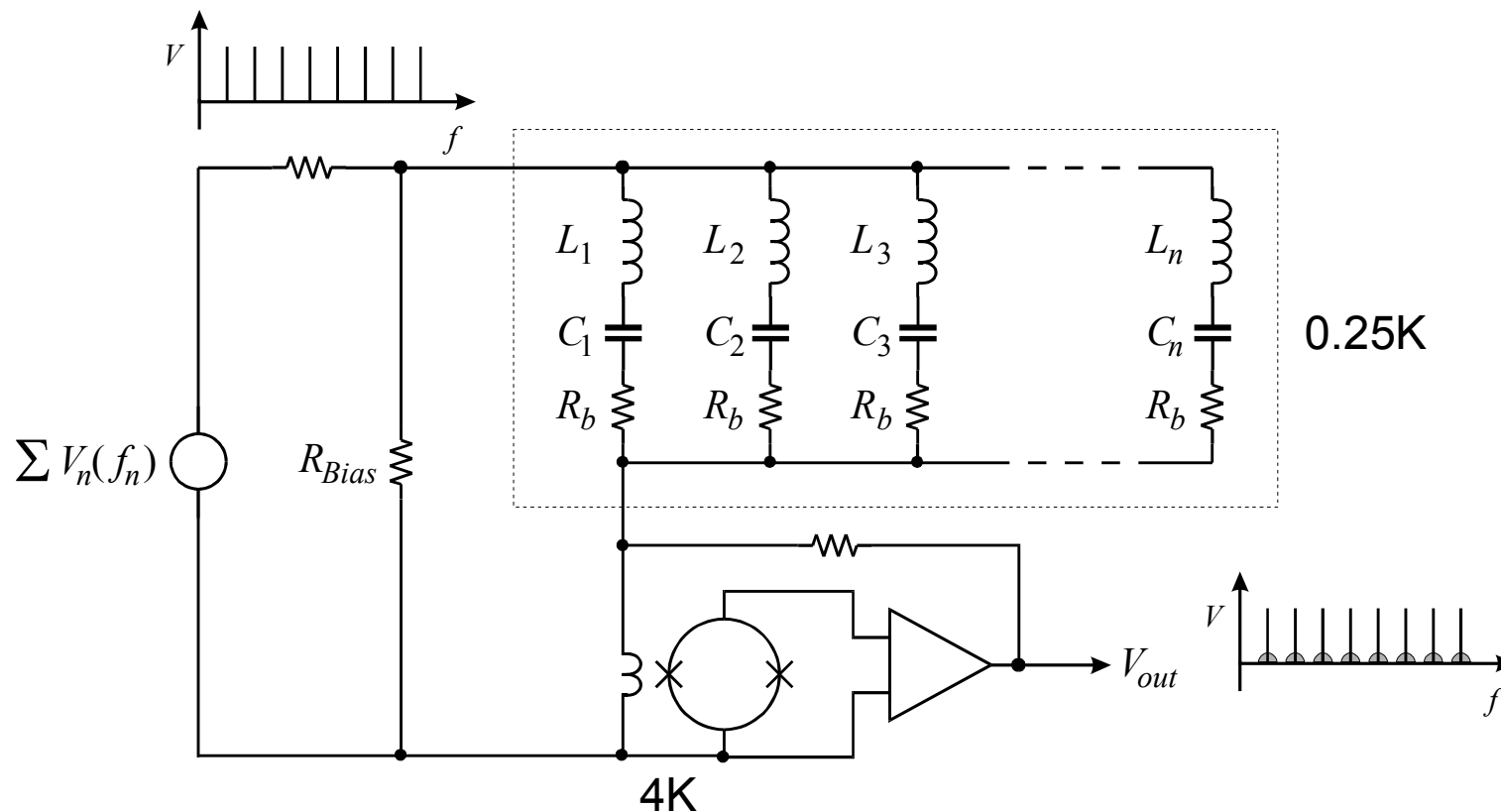
The power contained in the sidebands is equal to the modulation power, distributed equally between both sidebands.

Modulation Waveforms and Spectra



Carrier amplitude remains constant! All signal information in the sidebands.

MUX circuit on cold stage



- “Comb” of all bias frequencies fed through single wire.
- Tuned circuits “steer” appropriate frequencies to bolometers and limit noise bandwidth.
- Wiring inductance tuned out at resonance to reduce impedance.
- Current return through shunt-feedback SQUID amplifier (low input impedance).
- No additional power dissipation on cold stage (only bolometer bias power).

SQUIDs have limited signal range!

1. SQUIDs have periodic output

Maximum signals must remain within monotonic range

Dynamic range extended by

SQUID array
(100 SQUIDs in series)

Shunt feedback

2. Feedback must be active to maximum bias frequency (~MHz)

⇒ High loop gain-bandwidth product of 10s of MHz required

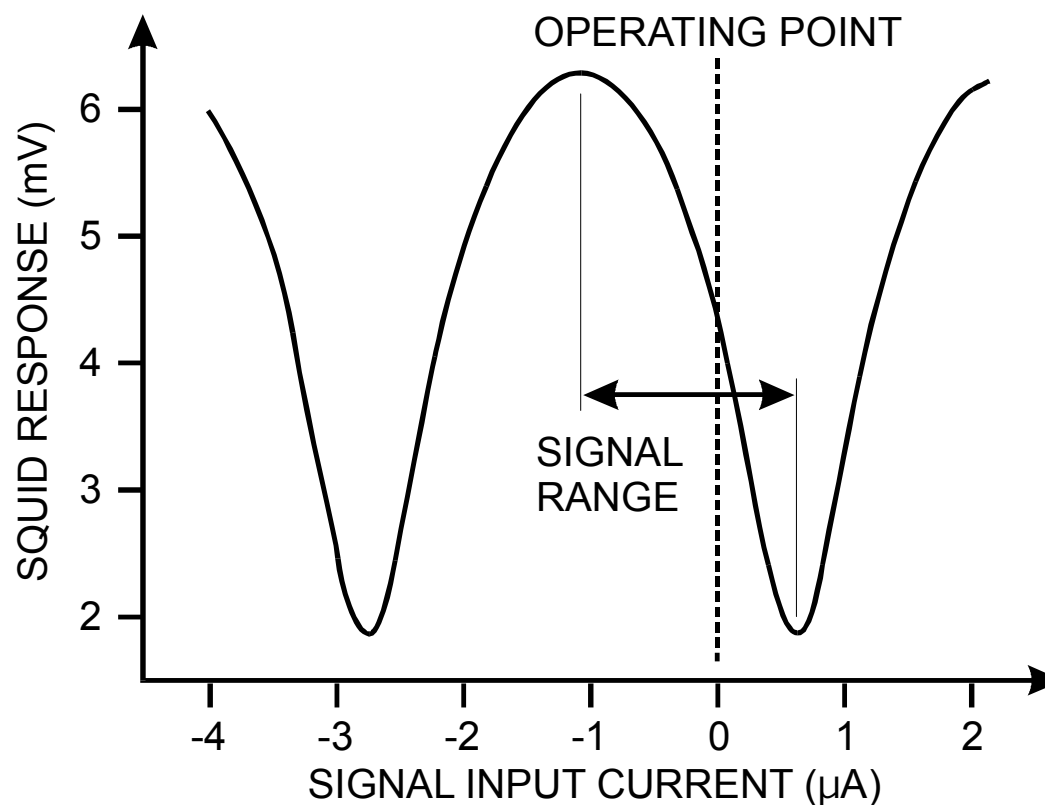
⇒ Limits wiring length to maintain phase margin for stability

3. In-situ characterization of individual SQUIDs required to determine operating point.

⇒ Digitally controlled bias scan and bias point

4. SQUIDs extremely sensitive to high-frequency RF pickup

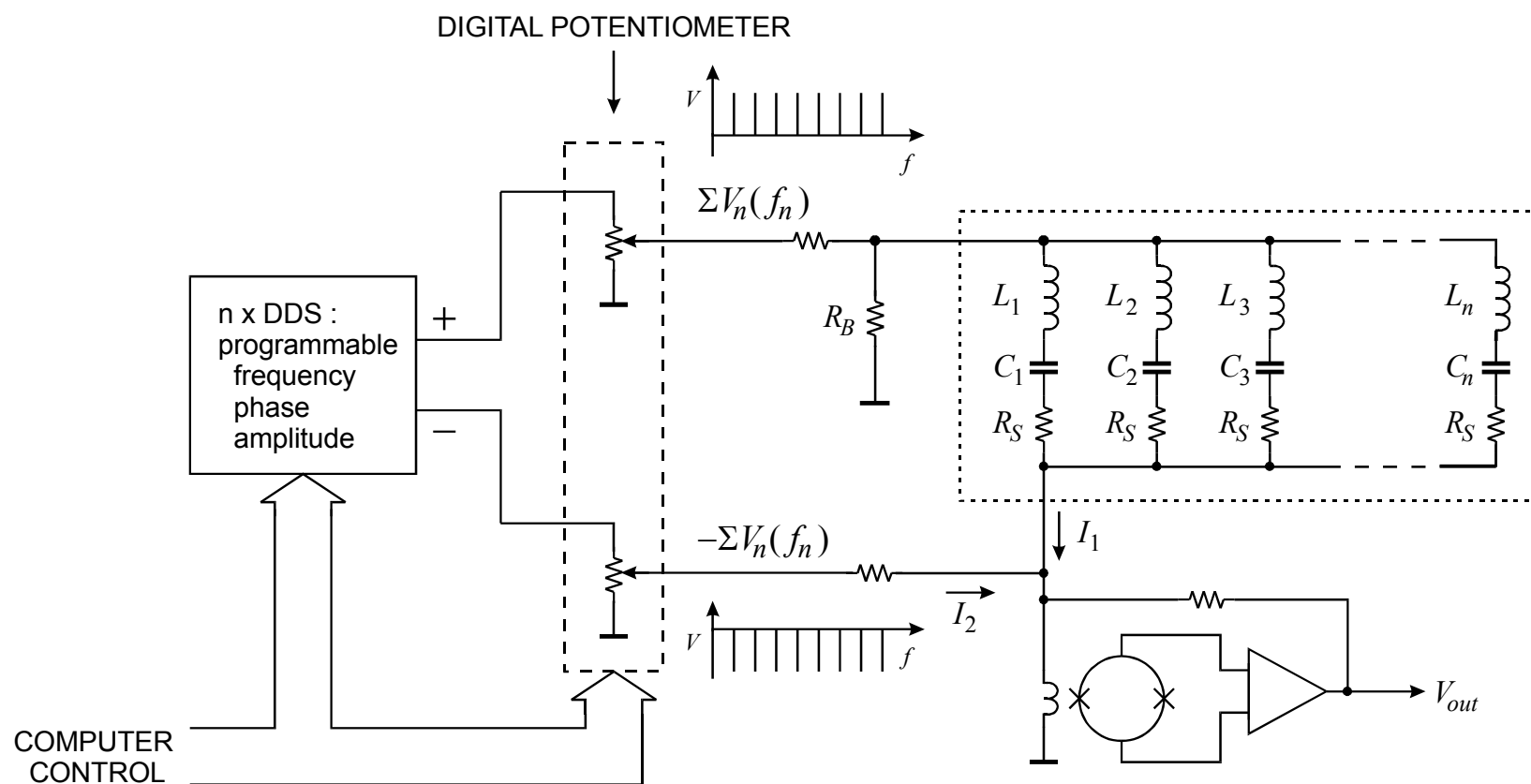
⇒ Digital crosstalk big problem as wide bandwidth connections to SQUID required.



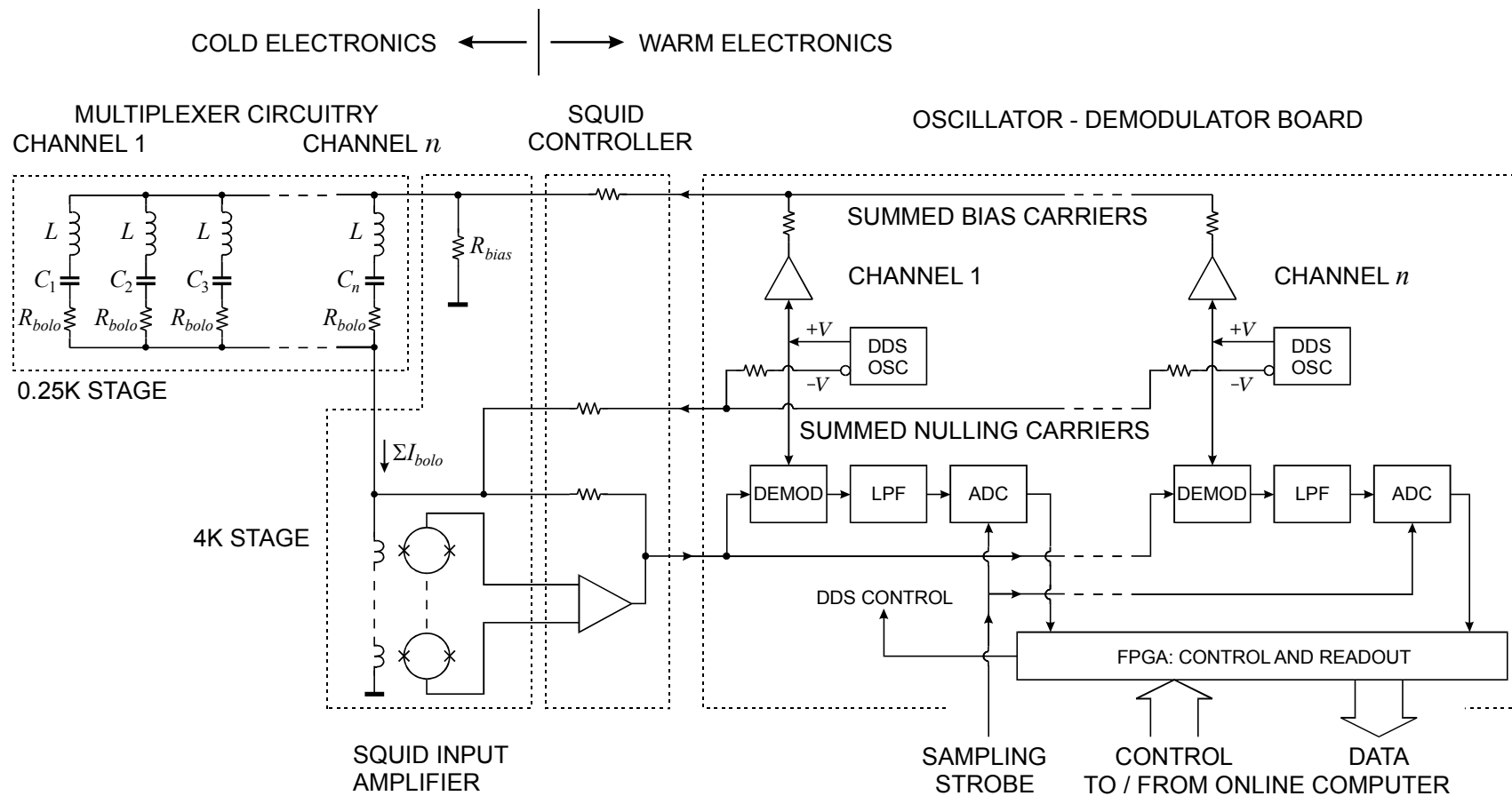
Carrier Nulling

Maximum input signal to SQUID is limited, even with feedback (“flux jumping”)

All of the information is in the sidebands, so the carrier can be suppressed to reduce dynamic range requirements.



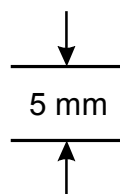
System Block Diagram



MUX chip (0.25K stage)

Superconducting spiral inductors
integrated on a chip

(fabbed by Northrup-Grumman)



Capacitors can be integrated with
inductors, but external chip capacitors
require less space.

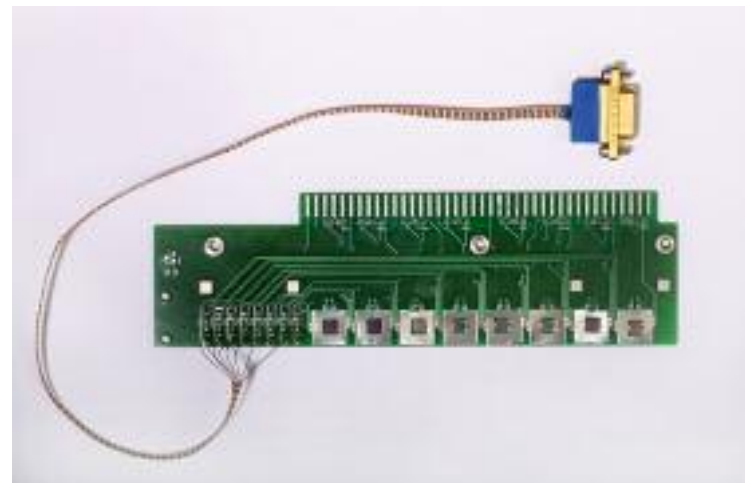
NP0 capacitors perform well at 4K



SQUIDs mounted as arrays of eight in magnetic shield (4K stage)

SQUID mounting board

SQUIDs mounted on Nb pads
to pin magnetic flux



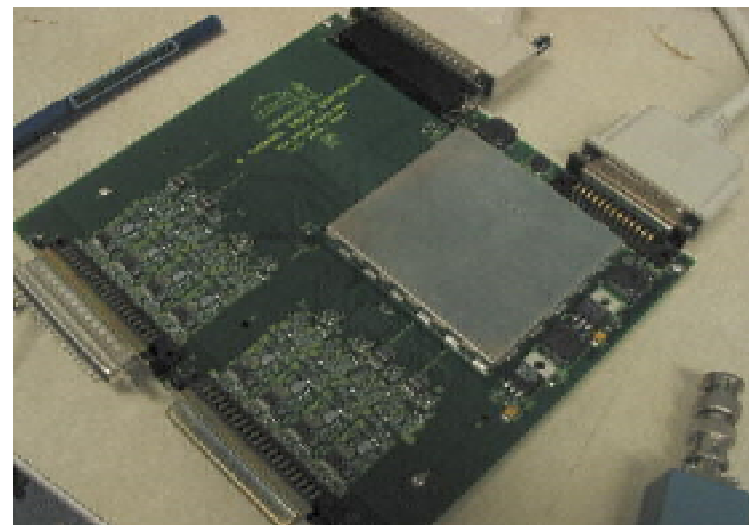
Magnetic Shield
(M. Lueker)



8-channel SQUID Controller

Computer-controlled (FPGA)
SQUID diagnostics
Open/closed loop
Switchable gain

SQUIDs VERY sensitive to pickup
(up to GHz), so local shielding of
digital circuitry is crucial.

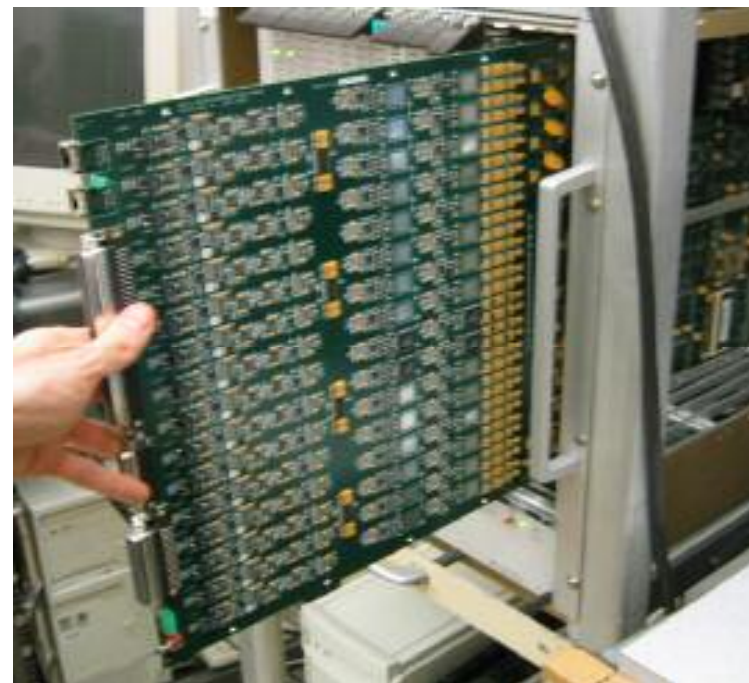


16-channel Demodulator Board

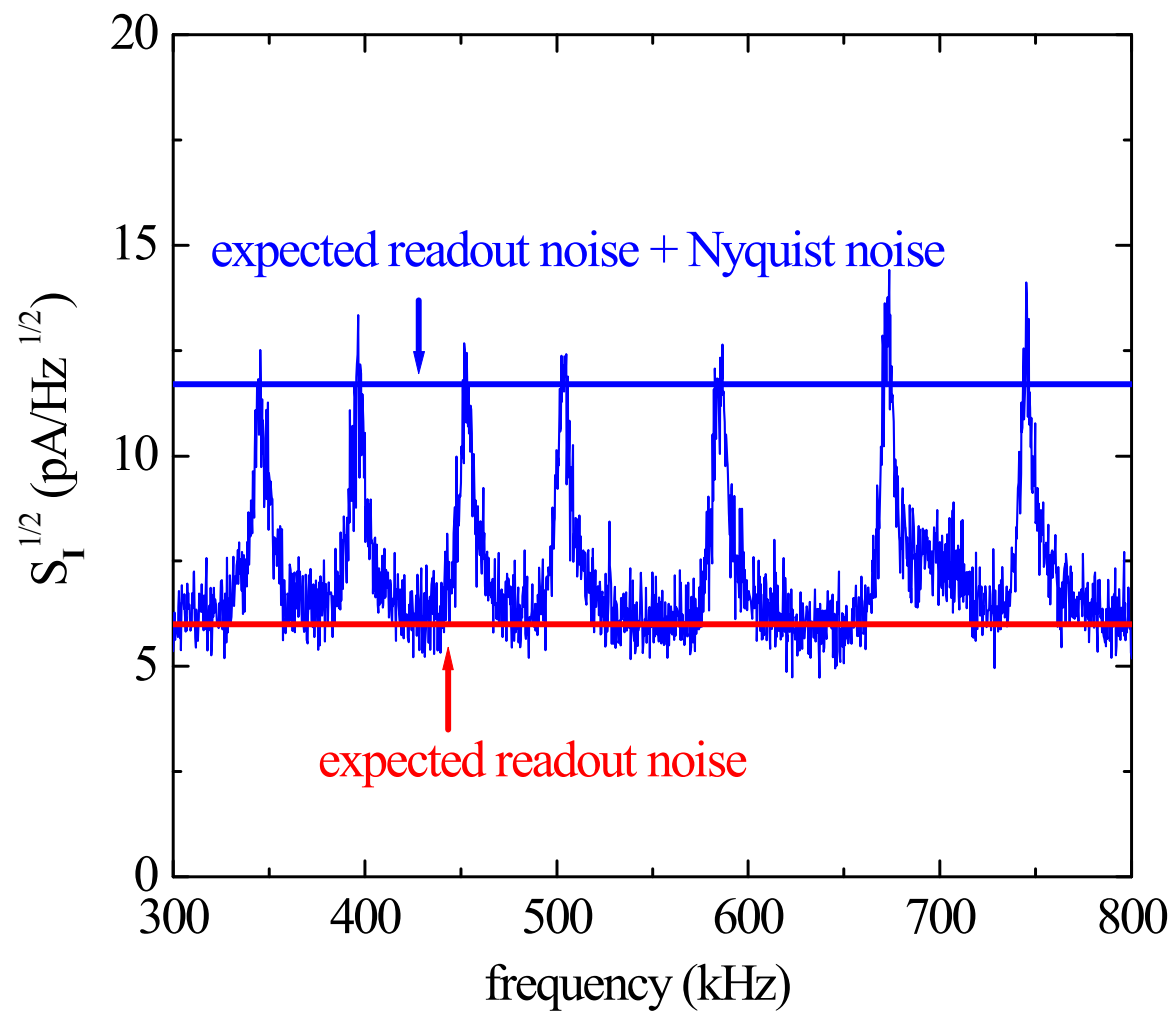
16 individual demodulator channels
1 DDS freq. generator per channel
On-board A/D
Opto-isolated computer interface

Design at LBNL
(M. Dobbs, J. Joseph, M. Lueker, C. Vu)

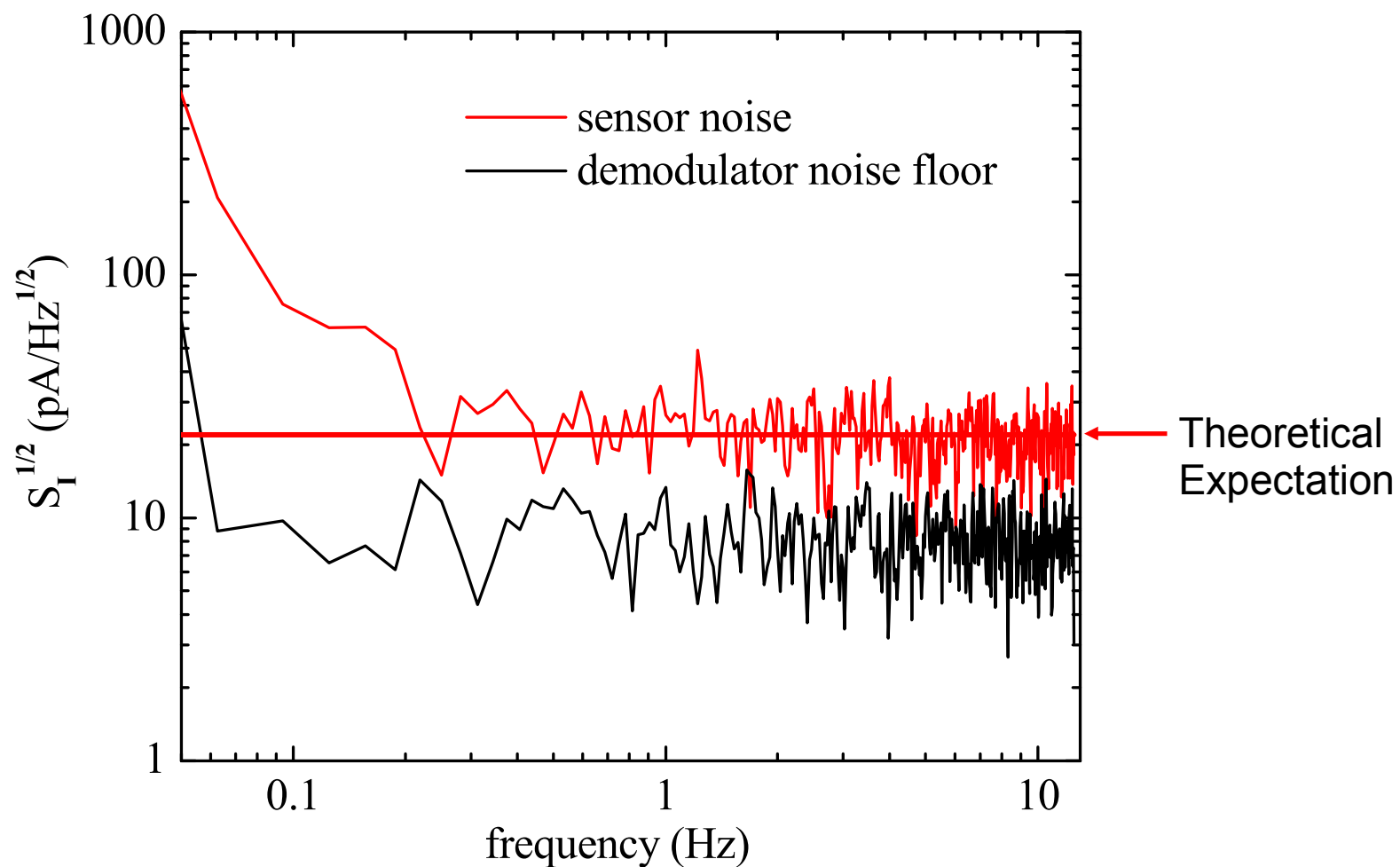
High Energy Physics experience essential!



Measured MUX Noise Spectrum at SQUID Amplifier Output (Trevor Lanting)



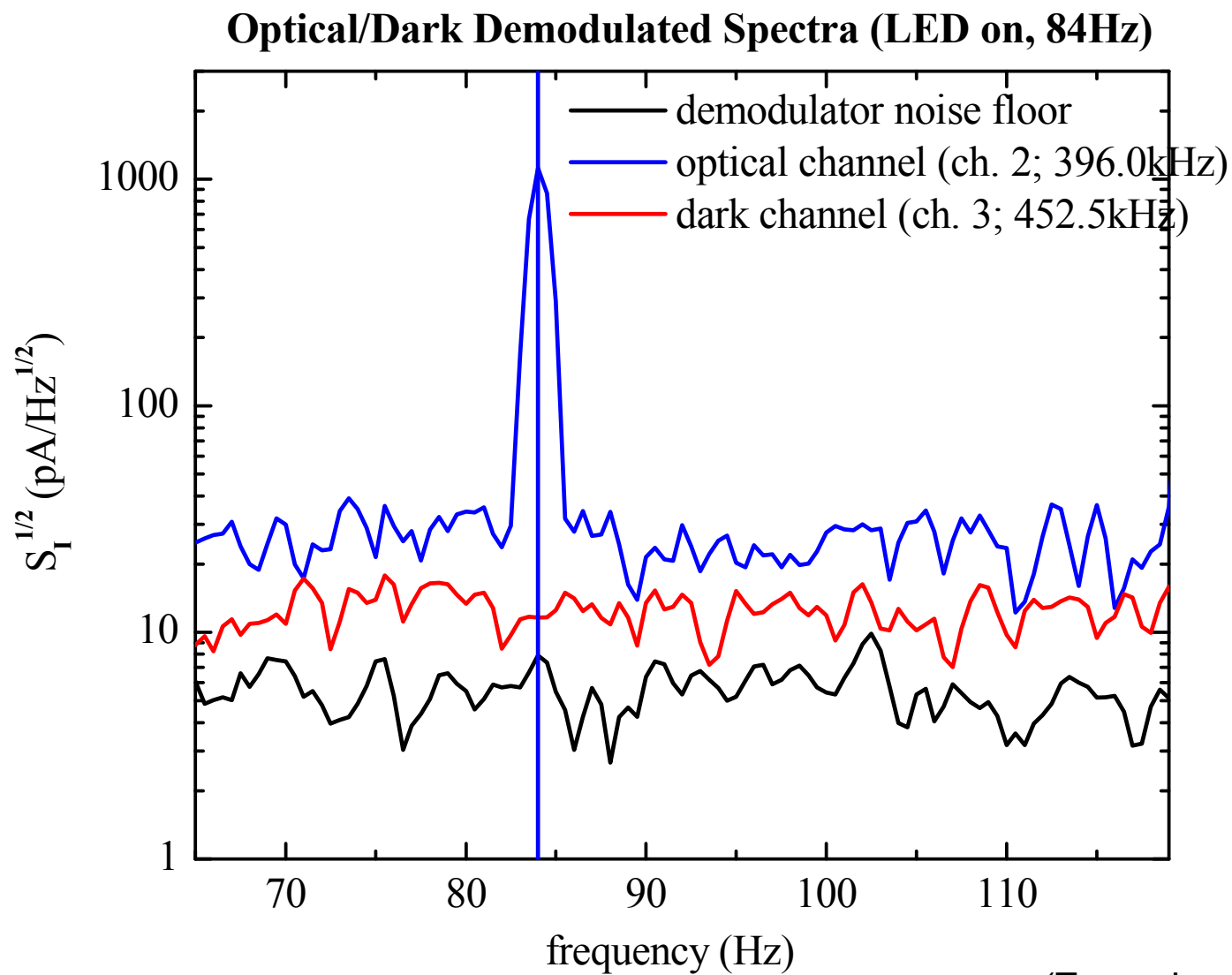
Measured Noise Spectrum in 8-Channel MUX System



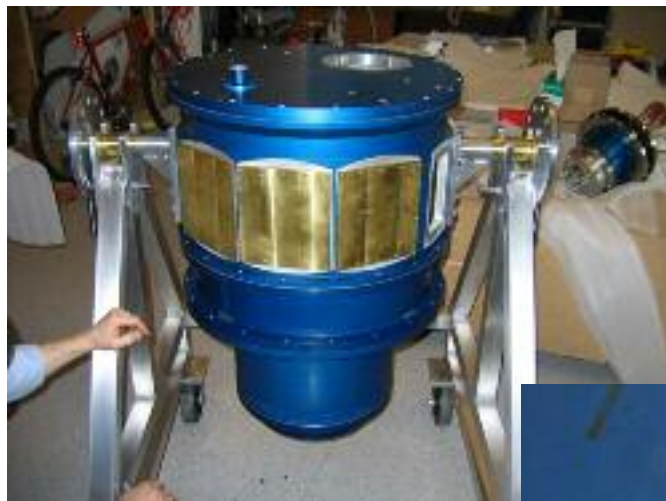
Sensor noise white above 0.2 Hz

(Trevor Lanting)

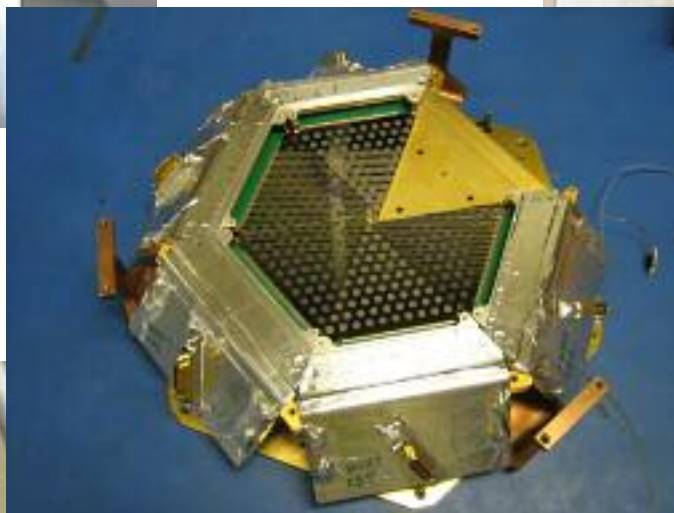
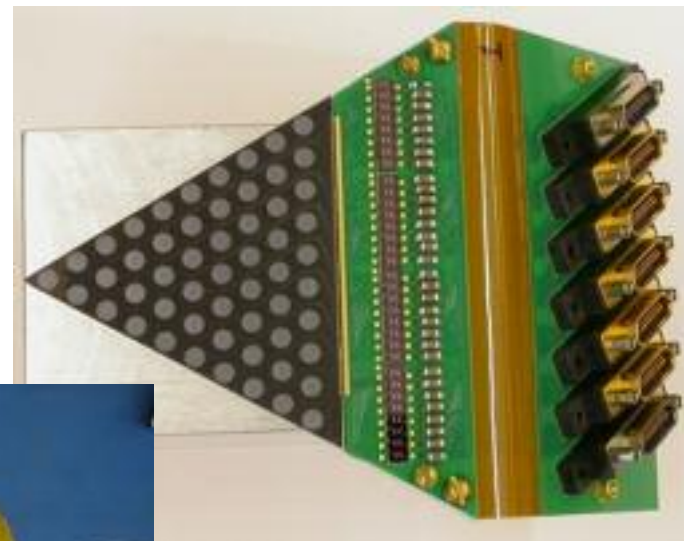
Cross-Talk < 1%



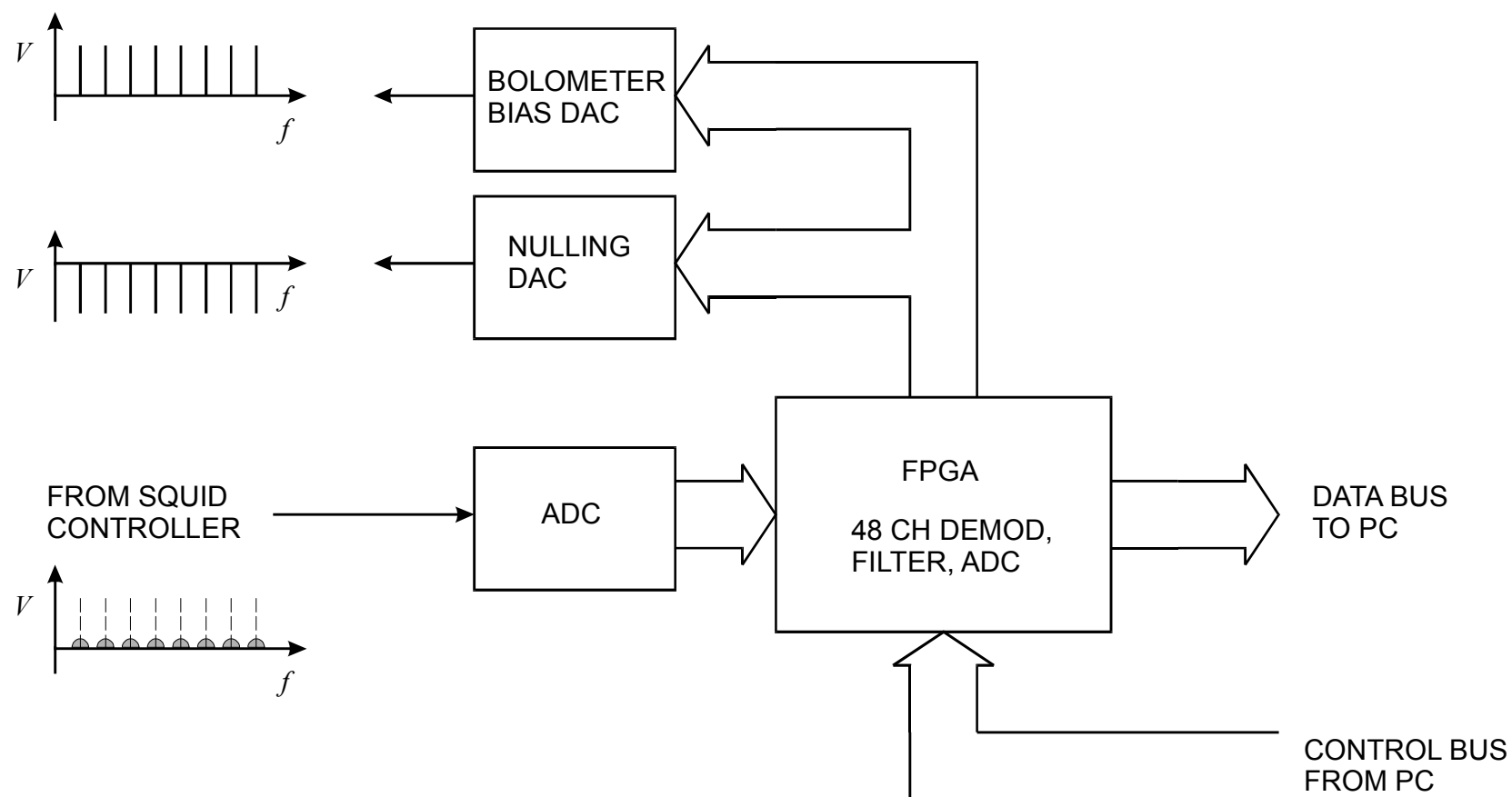
(Trevor Lanting)



APEX-SZ
MUXed Array
(SPT prototype)

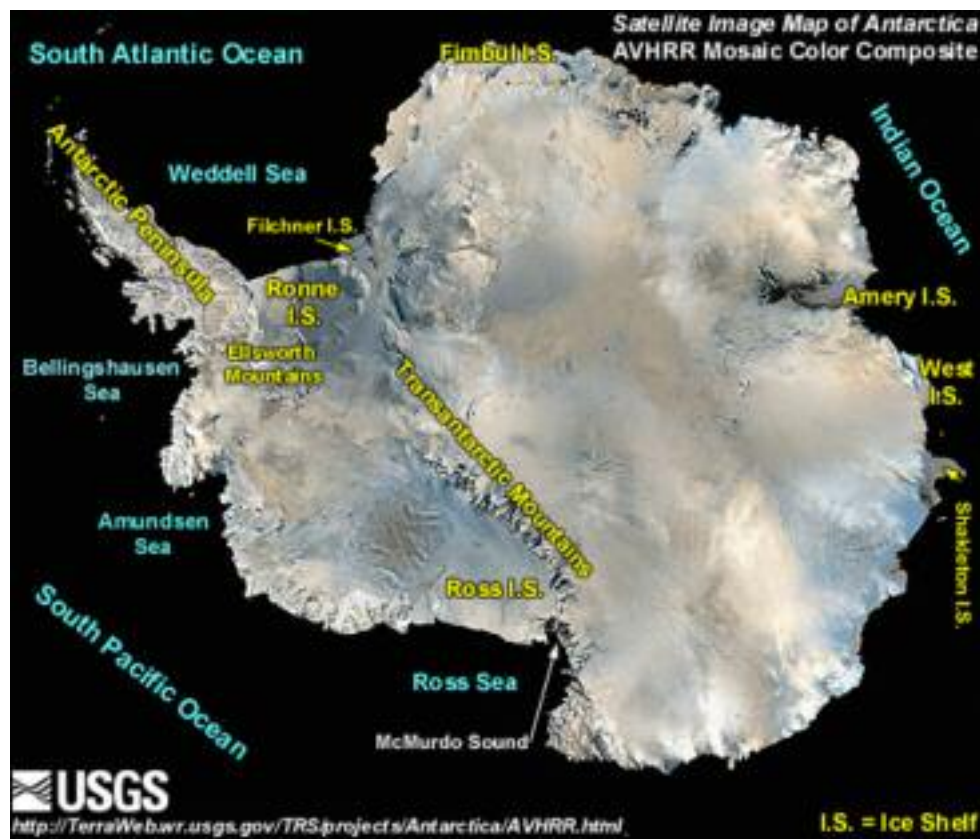


New Development: “Fully Digital” Demodulator (Matt Dobbs, LBNL/McGill)



- Prototypes of key components tested
- Substantial reduction in power \Rightarrow Balloon-borne experiments (e.g. EBEX)
Satellite mission (CMBPOL?)

Life at the Pole





Flights from Christchurch to McMurdo in C-17



Landing on the Ross Ice Shelf



Mt. Erebus – Active Volcano



Take the bus to McMurdo



Summer in McMurdo



The South Pole Telescope – Cosmology, Detectors, and Life at the Pole
UCSC Physics Colloquium, 11-Jun-2009

Helmuth Spieler
LBNL

Flight to the Pole



All flights to the Pole are on C-130 cargo planes.

Flights are cancelled if weather either at the Pole or for return landing at McMurdo is uncertain



Crossing the Transantarctic Mountain Range



The Geographical South Pole



The “Ceremonial South Pole”

Altitude 9300 ft. It's flat – the Pole is on 9000 ft of ice.



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UCSC Physics Colloquium, 11-Jun-2009

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Another View: Drilling Holes for Ice Cube



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South Pole Telescope and the Dark Sector Lab



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The optics cryostat (white) and receiver cryostat (red) removed from rcvr cabin



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Disassembled focal plane for upgrades



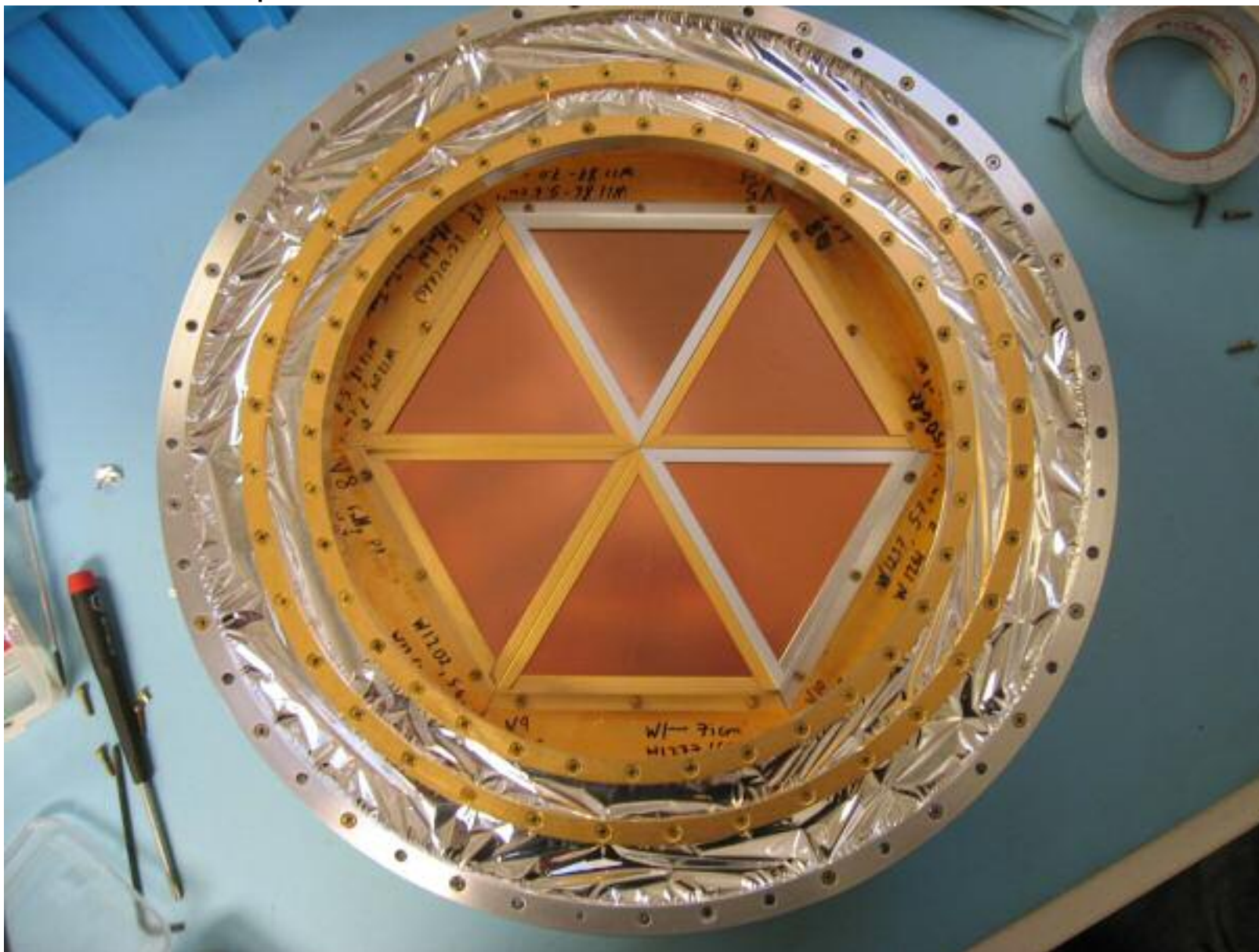
Wirebonding replacement SQUIDs



Sometimes some fine tuning is required



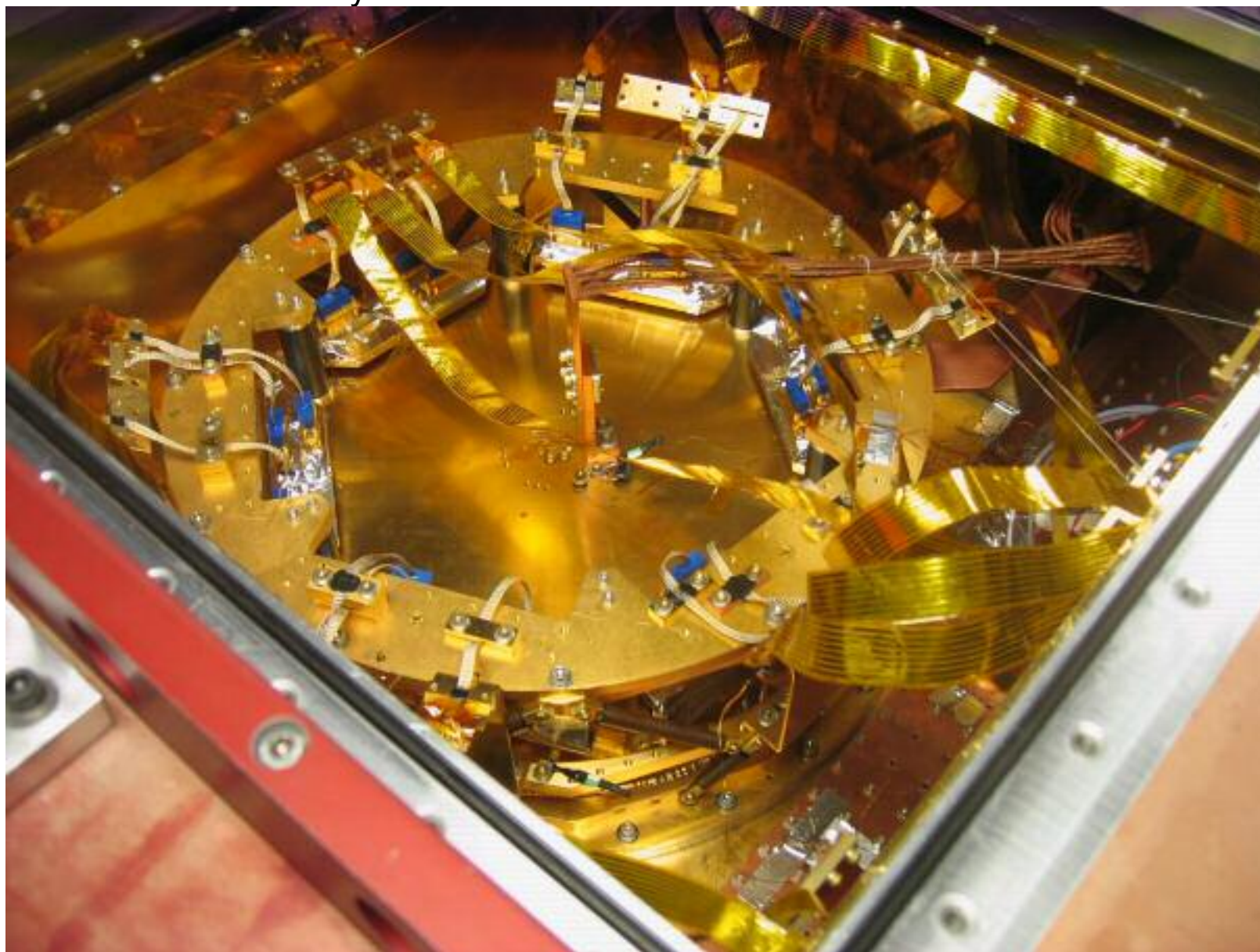
Assembled focal plane



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Innards of receiver cryostat



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Assembly area

Assembled cryostat beneath the open receiver cabin



Weather: Sun is up 24 hrs a day at about 23° above the horizon

Typical temperatures (2007-8): -40°C with -55°C wind chill
in winter typ. -70°C

Full gear for cold days, ...

but sometimes its “balmy”
(-20°C with little wind)





Visibility can change quickly



When it gets worse, follow the flags
(... better follow the right ones)





The main station
Summer population ~250
Winter ~60

The galley (food available 24 hrs)



Food is stored outside (at the Pole it's always well below freezing)



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The Annual Race Around the World



The House Science Committee Playing Golf at the Pole



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Takeoff for McMurdo



On the Ross Ice Shelf



2009 Flight McMurdo to Christchurch – 8 hrs “business class” in a Royal New Zealand Air Force C-130 (fuel economy much better than C-17)



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Summary

- South Pole Telescope in its 3rd year of operation, taking data efficiently
- Current CMB experiments achieve $10^2 - 10^3$ fold improved sensitivity
- Monolithic fabrication technology provides wafer-scale TES kilopixel arrays
- Frequency-domain MUXing demonstrated
 - Zero power dissipation at 0.25K focal plane
 - <1% cross-talk
 - Very insensitive to vibration
 - Negligible increase in noise
 - Conceptually simple, but many crucial details
- System incorporates techniques from
 - Cryogenics and superconductivity
 - RF communications (old and new)
 - Low noise analog electronics
 - High Energy Physics
- Collaboration between University and National Lab was essential, although not supported by funding agencies (NSF – DOE)

Enough Talk – the End



J. Dana Hribes
2008